

# **An Active Filter Approach to the Reduction of the DC Link Capacitor**

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Project ID:  
ape\_01\_ozpineci

# Overview

## Timeline

- Start date – Oct. 2007
- End date – Sep. 2009
- Percent complete – 50%

## Budget

- Total project funding
  - DOE share: 100%
- Funding received in FY08: \$158K
- Funding received in FY09: \$294K
- Funding requested for FY10: \$0K

## Barriers

- **Barriers**
  - DC link capacitor problems: size (35% of the inverter volume), weight (23% of the inverter weight and cost (23% of the inverter)
  - High temperature capacitors
  - High active power filter device losses.
- **Vehicle Technology Program Targets**
  - DOE 2015 targets: 105°C Coolant
  - DOE 2015 target: 12 kW/l

## Partners

- UT (literature survey, modeling and simulation)

# Objectives

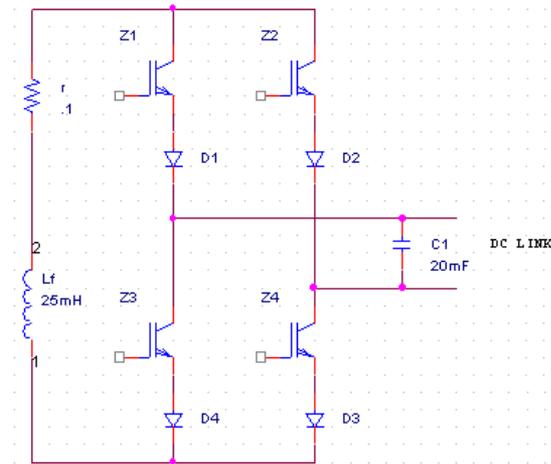
- **The objective of this project is to develop an active power filter (APF) to replace the bulky DC link capacitor.**
- **The APF is expected to**
  - **Imitate what a DC link capacitor does**
  - **Be much smaller size than the DC link capacitor**
  - **Be an enabler for higher temperature operation**
- **FY09: Develop new topologies and designs to reduce the efficiency problems associated with the high frequency switching and high inductor current the present APF designs require.**

# Milestones

| FY08  |   |   | FY09  |   |   |
|---|---|---|---|---|---|
| October to January  | February to July  | August to September   | October to February   | March to June                                 | July to September                                   |
| Establish the performance requirements for an active filter | Simulate an active filter that can replace a dc link capacitor in a traction inverter | Assess the simulation results, loss calculations, and comparisons against baseline technology | Analyze methods to reduce the frequency and operating current of active filter to improve the performance | New control methods simulation and evaluation | Build a benchtop active filter for a 55 kW inverter |

# Approach

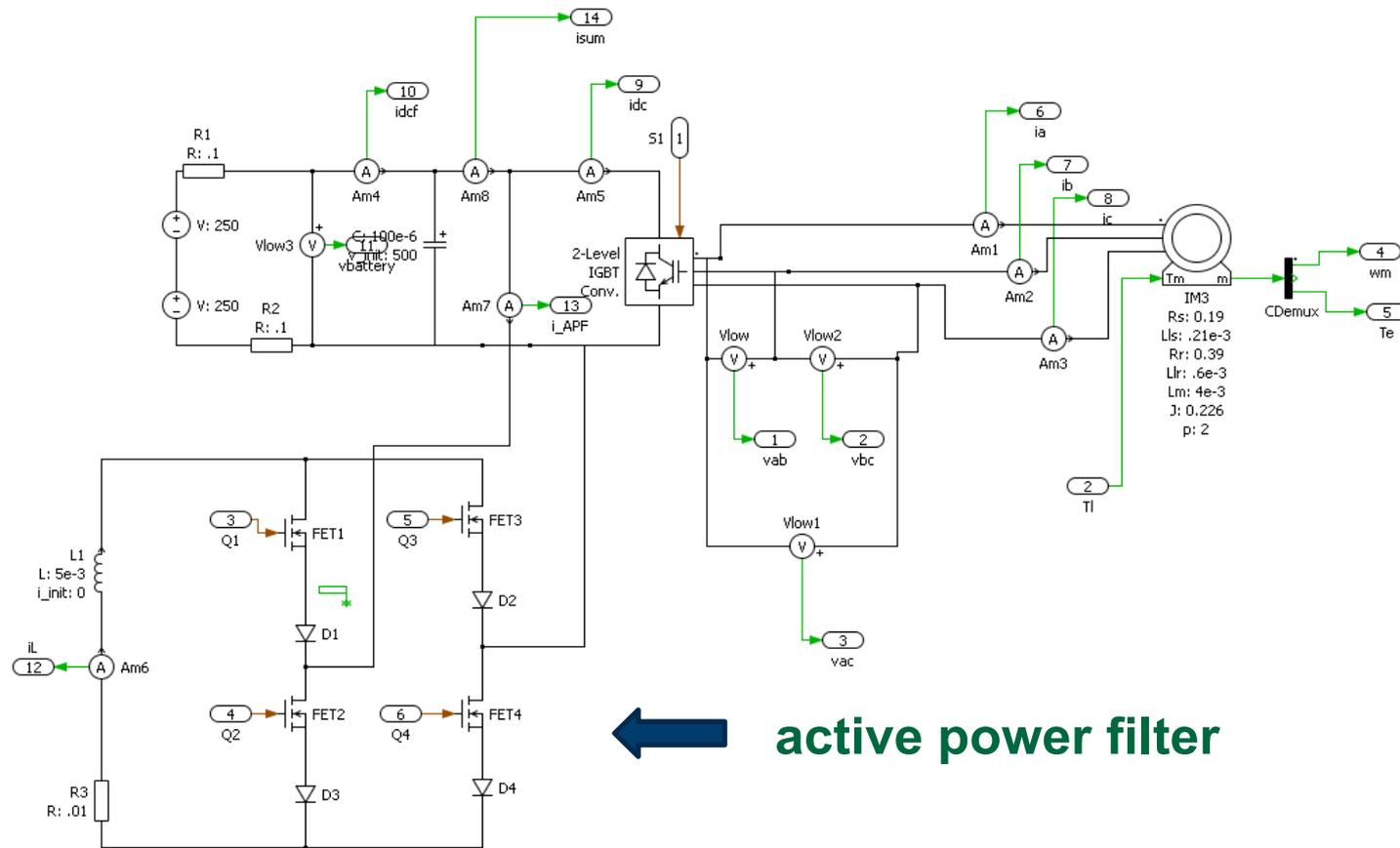
- **An active filter with a much smaller capacitor (1/10th-1/20th of the Camry capacitor) and inductor can be used in the DC link together with semiconductor switches to replace the DC link capacitor.**



- **Impacts**
  - **Reduced size and cost**
  - **May provide more cost-effective solution for high temperature operation**

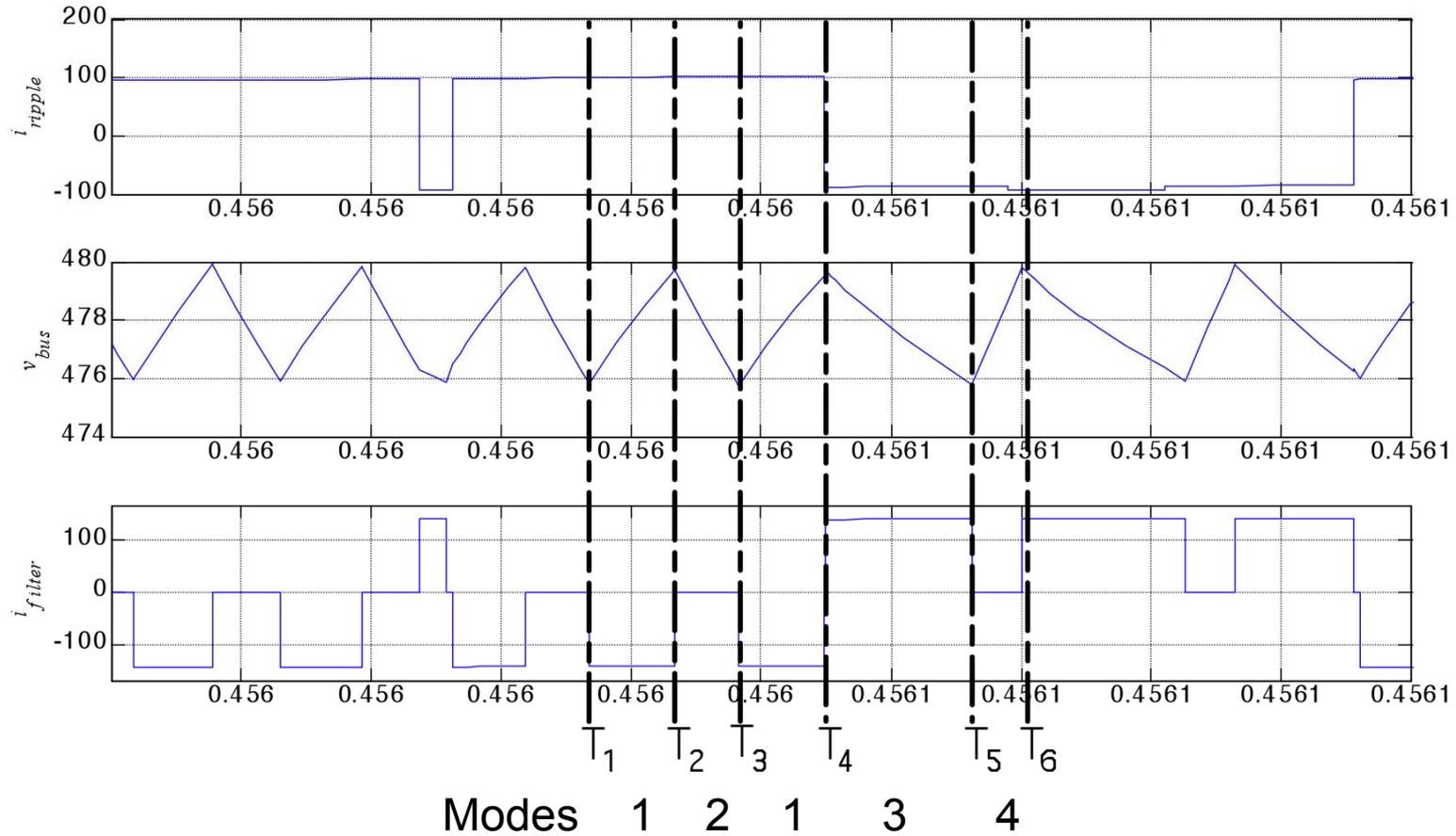
# Accomplishments

A Matlab/Simulink simulation model of a traction drive system was used to establish the performance requirements for an active power filter.

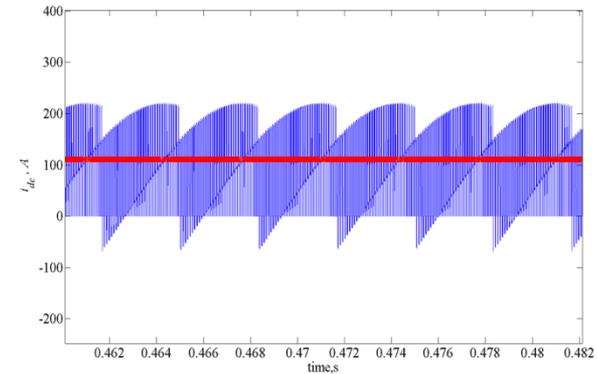
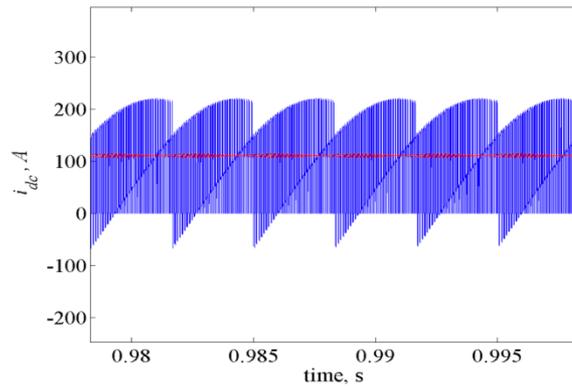


← active power filter

# Operation Waveforms

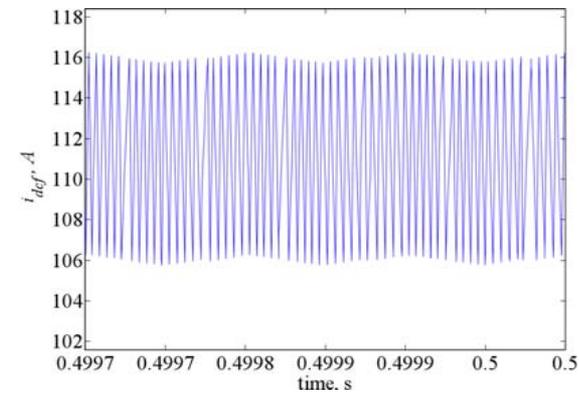
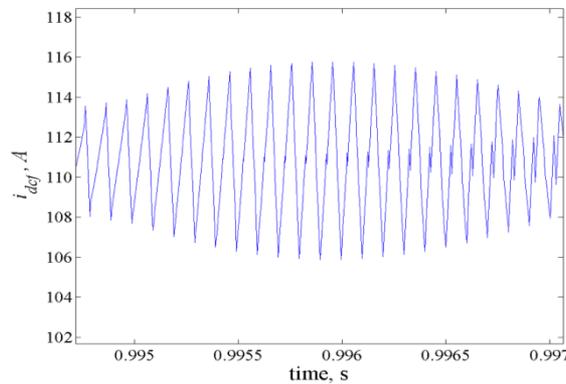


# Simulated Operation Waveforms

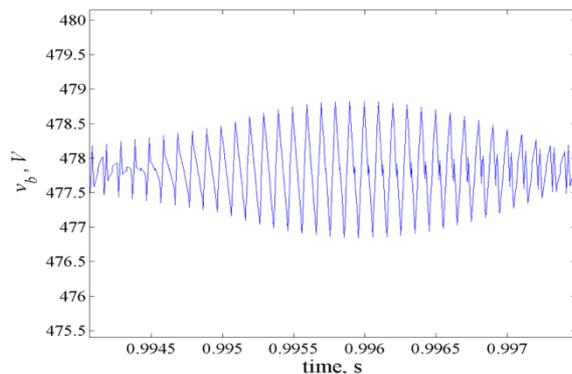


DC Link  
Current

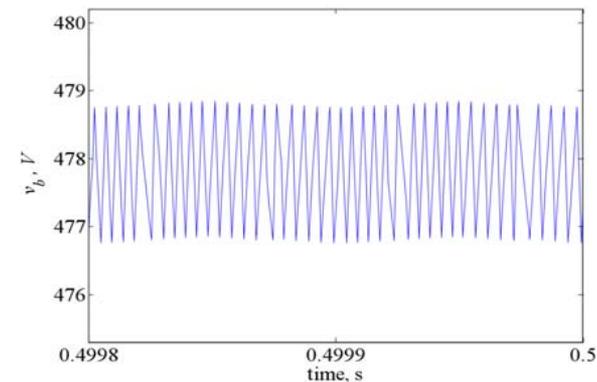
Case 1-  
w/  
capacitor



Case 2 –  
w/ APF



DC Link  
Voltage



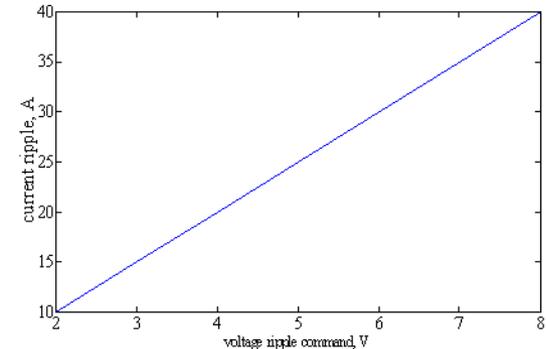
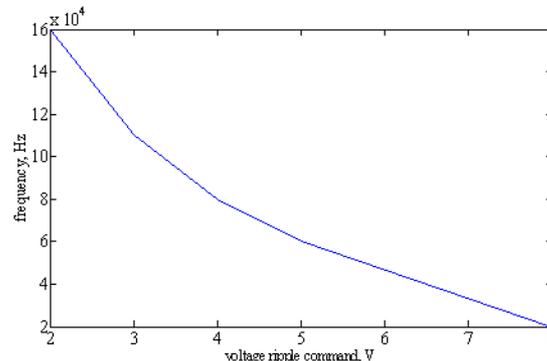
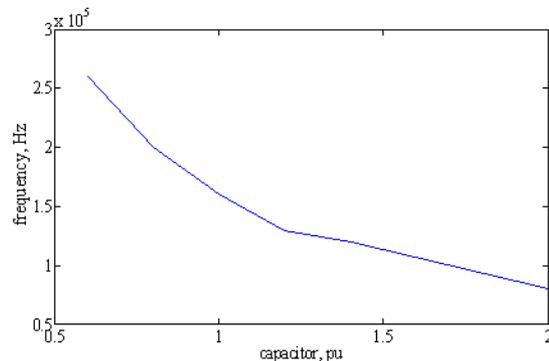
# Comparison – APF vs Capacitor

|                             | Case 1 (capacitor)                          | Case 2 (APF)   |
|-----------------------------|---|--|
| DC Link Capacitor           | 2200 $\mu$ F                                | 100 $\mu$ F  |
| APF Inductor                |   | 25mH   |
| APF Switching frequency     |   | 130kHz*  |
| Extra Components            |   | 4 switches and 4 diodes (could be 4 reverse blocking IGBTs)+inductor |
| APF Inductor Current        |   | 100A* dc   |
| Peak-to-peak voltage ripple | 2V (0.4% of DC voltage)                     | 2V (0.4% of DC voltage)  |
| Peak-to-peak current ripple | 10A (4.5% of the unfiltered ripple current) | 10A (4.5% of the unfiltered ripple current)                          |
| DC link voltage             | 500V  | 500V   |
| Output Power                | 30kW  | 30kW   |

\*At lower output power lower switching frequency and lower inductor current will be used.

# Parametric Study

- **Switching frequency is inversely proportional with the smoothing capacitor size and the DC link voltage ripple hysteresis band limits**
- **The DC link voltage ripple hysteresis band limits are directly proportional with the amount of DC current ripple**



# Efficiency is a problem...

- **A 100A - 5mH inductor has an internal resistance of  $0.01\Omega^*$  and a 2.5mH inductor has half of that value**
- **Typical losses in the inductor for 100A**
  - 5mH inductor, 100W (0.33% for 30kW)
  - 2.5mH, 50W (0.17% for 30kW)
- **The inductor current varies with the output power**
- **Major losses occur in the devices (IGBTs 1427W – Diodes 460W)**

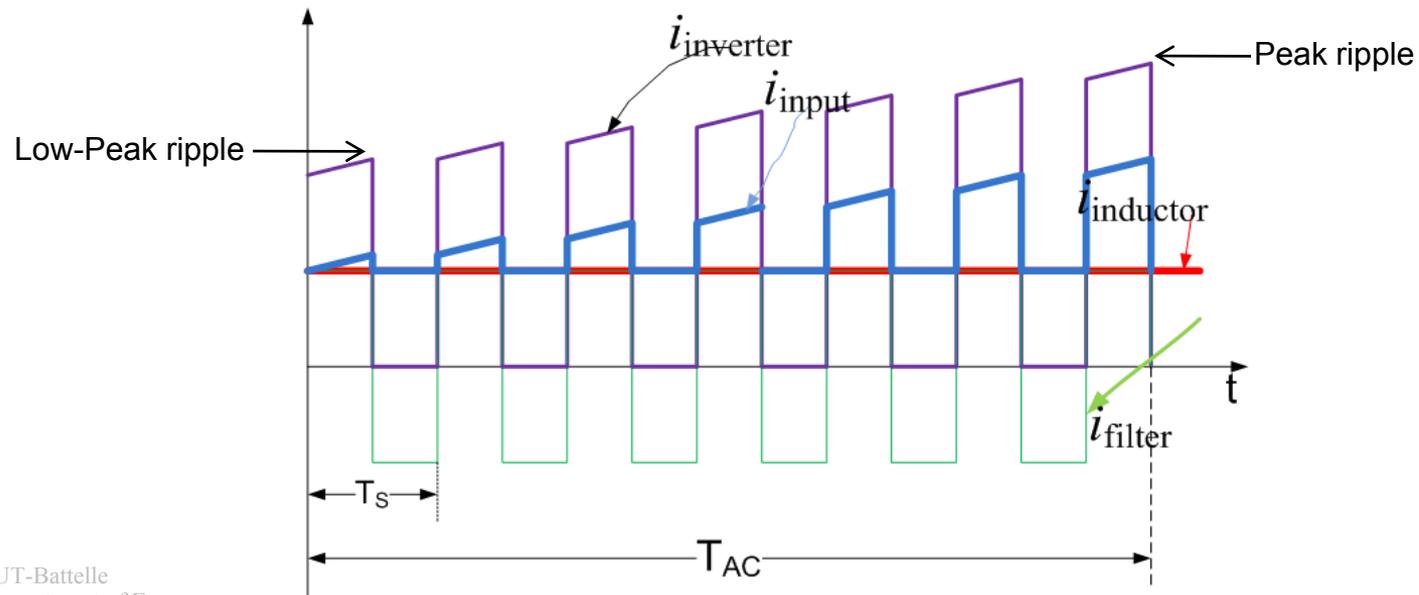
*\*[www.hammondmfg.com](http://www.hammondmfg.com)*

# Improved APF

- **A new control method with**
  - **Reduced APF switching frequency – the APF can be switched at the inverter switching frequency**
  - **Reduced inductor current – half of what the original APF control needs**
  - **Slight increase in the DC-link capacitance**
- **Impact on APF losses compared to the original method**
  - **Reduction in switching losses to less than 20%**
  - **Reduction in conduction losses to less than 25%**

# Comparison

|                     | Active power filter (APF)                                       | Improved APF                               |
|---------------------|---|--|
| Principle           | Increase the ripple frequency to reduce the smoothing capacitor | Compensate part of the ripple current      |
| Inductor current    | Higher than half the peak ripple (140A)                         | Higher than half the low-peak ripple (75A) |
| Operating frequency | 10x inverter frequency  | Inverter frequency                         |
| Capacitor size      | Small (100 $\mu$ F)   | Small (>100 $\mu$ F, <500 $\mu$ F)         |



# Future Work

- **Investigate topologies that will reduce the filter inductance requirements and improve the APF efficiency**
- **Demonstrate the improvements in the topology**
- **Demonstrate the successful operation of the APF replacing the DC link capacitor**
- **Develop a topology that is expected to**
  - **weigh half as much and**
  - **occupy less than half the space, when compared to the Camry DC link capacitor.**

# Summary

- **The APF functions as expected but there are some practical barriers that need to be overcome.**
  - **Device losses can be reduced by**
    - Using less switches and diodes or using a *different topology*
    - Reducing the inductor current
    - Reducing switching frequency
  - **Inductance value and associated inductor size**
    - Inductance value determines the stiffness of the dc current
      - Low inductance causes low frequency voltage ripple
    - An optimum inductance value is required
- **A new APF control method has been developed that can reduce the losses on the APF and the size of the inductor with a slight increase in the capacitance.**