Wireless Charging of Electric Vehicles

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Oak Ridge National Laboratory

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Project ID: VSS103

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Program Overview

<u>Timeline</u>

- Project start date: Oct. 2012
- Project end date: Scheduled for April 2016
- 98% Complete (reporting, papers, etc.)

Budget (DOE share)

- DOE funding : \$8.0M
- Partner funding : \$2.6M

Barriers

- Transfer from laboratory set-up to integration prototype development
- Ability and availability of components for WPT requirements
- Interoperability with different vehicle energy storage system requirements.
- Lack of Standardized Test Protocols

Partners

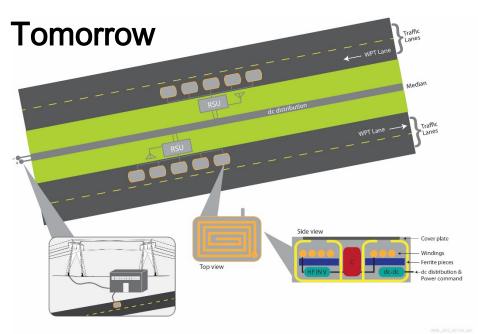
- Oak Ridge National Laboratory (Project Lead)
 - Power Electronics & Electric Machinery Group
 - Center for Transportation Analysis
- Toyota (CRADA)
- Evatran (Plugless power)
- Clemson University ICAR Center



Project Objective and Relevance

- Advance technology maturity, identify commercialization, standardization and safety of wireless charging technology
- Supports major LD Vehicle Systems (VS) powertrain electrification goals:
 - Demonstrate market readiness of gridconnected vehicles
 - Develop methods to reduce impact on infrastructure due to EV charging.
 - Address codes and standards needed to enable wide-spread adoption of electric-drive transportation technologies.
- Directly supports VS component and systems evaluation.
 - Supporting J2954 standards
 - Component efficiencies highlighting system efficiencies and project deliverables







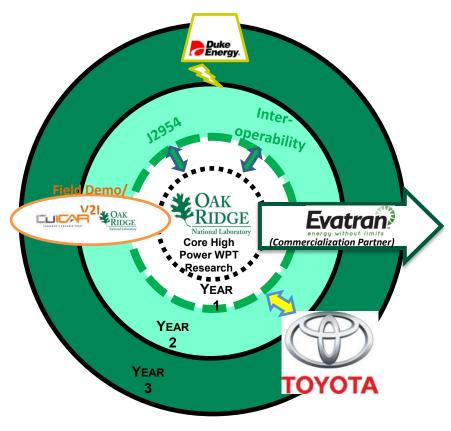
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Objective and Outcome

Overall goal: Coordinate multi-party team activities to integrate the technology developed in the lab to the vehicles with different WPT charging levels (WPT Level I-II) and different vehicle ESS and interface requirements.

Overall Program Outcome:

- Develop fundamental knowledge base for the technology to fill the gaps for commercialization.
- Work with partners to overcome the challenges of vehicle integration.
- Validate system through testing and generate valuable research data.
- Provide unbiased data to promote technology standards.





Partners / Collaborators

Organization		Type of Collaboration/Coordination	
Evatran: energy without limits	Evatran - Plugless Power	WPT packaging, vehicle integration, vehicle testing	
	Clemson University ICAR	Communications technology, demonstration site	
ΤΟΥΟΤΑ	Toyota Motor Corp	Demonstration vehicles (Prius Plug-in, Scion IQ-EV, RAV4) and integration support, CAN	
Duke Energy.	Duke Energy	Grid readiness and interaction	
uluilu cisco	CISCO Systems	DSRC Communications	

 ORNL supports SAE J2954 Wireless Charging Standards Development Committee and its subcommittees.

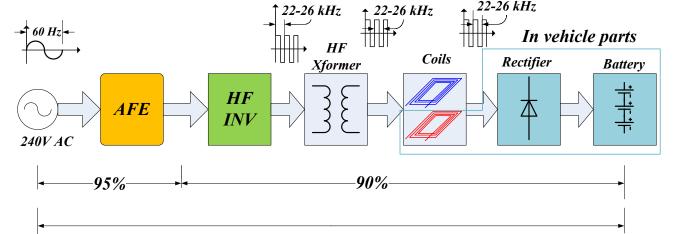
Milestones

Date	Milestones and Go/No-Go Decisions	Status
Nov-2013	Milestone: WPT efficiency >85% wall to battery (or equivalent) at 6.6 kW power.	Successful demonstration of bench top prototype technology at ORNL > > 85% @6.6kW (required) > Demonstrated 10kW (progress towards high power) > Met the IEEE and ICNIRP standards
July 2015	Milestone: Integrate WPT System into commercial PEV's. Demonstrate 85% efficiency is retained at >160mm airgap at >6.6kW power transfer to the load.	ORNL, Evatran, and Cisco completed integration of WPT system into Toyota vehicles (Prius and Scion iQ).Demonstrated interoperability with two vehiclesClosed loop automated charging process operation with 85%@6.6 kW was demonstrated at ITIC facility
November 2015	Milestone: Evaluation of the OEM vehicle with fully integrated WPT system by an independent laboratory	 INL independently tested the system at different test conditions and validated: Power transfer level (>6.6kW), Efficiency target (>85%), Misalignment tolerant (up to +/- 40mm), Electric and magnetic fields (<6.25uT, <87V/m).
March 2016	Milestone : Demonstrate progress toward 20 kW static and dynamic wireless charging using an OEM vehicle	Excluding PFC, DC-to-DC efficiency >95%, power transfer >20kW Electric and magnetic fields (<6.25uT, <87V/m).



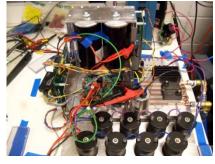
Technical Accomplishments: Test Bench Demo-FY13/14 Milestone: Overall System Architecture

- Targeting grid side regulation with a single grid side unit adapting the requirements from different vehicles with minor hardware modifications on each vehicle.
- Built a control system that allowed fully automated operation, control, monitoring, and switch between operating modes.



Coils

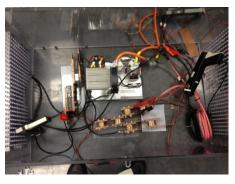




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Vehicle Integration : Summary and Testing

- System designed during the initial phase integrated into the vehicles with all functionalities including:
 - Alignment (Evatran system leveraged and integrated)
 - Radio communications for vehicle side feedback and controls (Cisco and Clemson University ICAR)
 - Start and stop charge
 - Orderly and emergency shutdown procedures
- Demo at ITIC facility in July 2015.



Vehicle Integration : Summary and Testing

Performed the Phase #2 demos in July 2015 with Prius Plug-in and Scion iQ

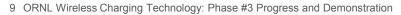


 Demonstrated fully automated operation, 6.9kW power transfer at 160 mm airgap, 85.4% efficiency (208-209Vac)

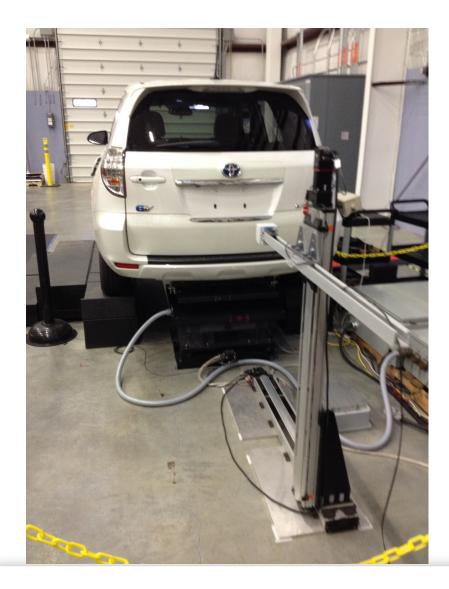




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INL Testing Summary Test setup:



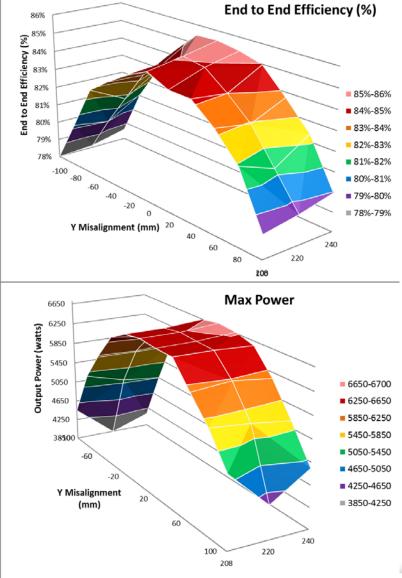




INL Testing Summary

- 6.6kW, 160mm magnetic airgap, 85.50% end-to-end efficiency (up to 6.8kW tested)

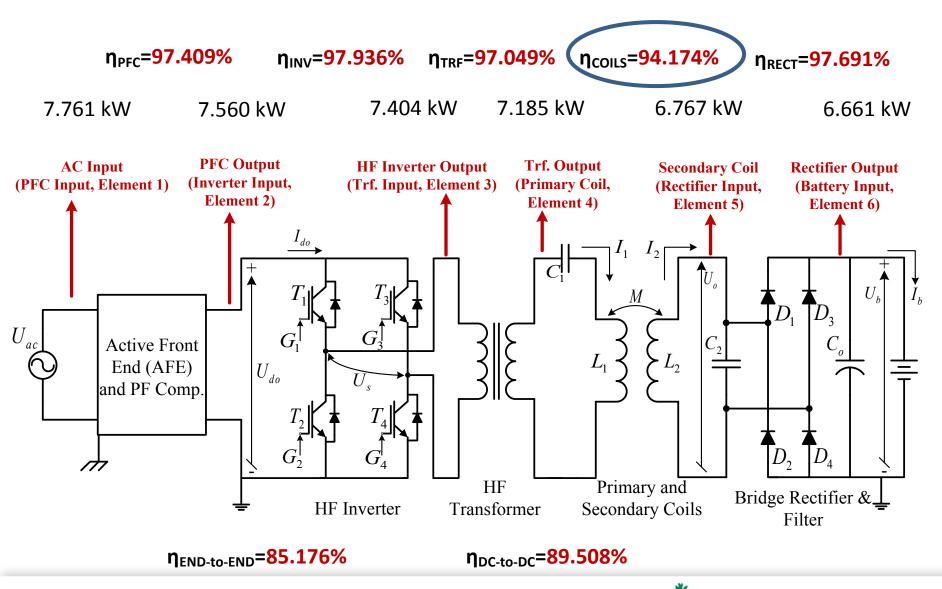
Misalignment [mm]	Output (battery) power [W]	Efficiency [%]
-100	4104	78.57
-80	5054	81.10
-60	5920	82.88
-40	6348	84.36
-20	6642	85.44
0	6715	85.50
20	6667	85.31
40	6567	84.97
60	6143	83.74
80	5573	82.38
100	4938	79.95



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Static WPT Demonstration -6.6kW at ORNL – With Interoperable Coils

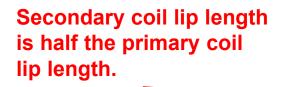


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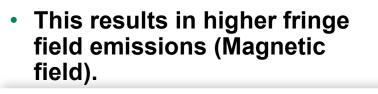
Static WPT System Improvements at ORNL

- All power conversion stages are at least 97% or more efficient except coil-tocoil efficiency.
- ORNL evaluated that reduced coil-to-coil efficiency is due to the dimensional difference in primary and secondary coils.
- According to SAE definition, unmatched coils are interoperable coils.
- Efficiency expectation of systems with interoperable coils is 80% instead of 85%.
- Due to the smaller size secondary coil, <u>not all the</u> <u>field generated by primary</u> <u>coil can be captured by</u> <u>secondary.</u>



Secondary coil is shorter by ~2 inches from each side (which reduces efficiency)

#3

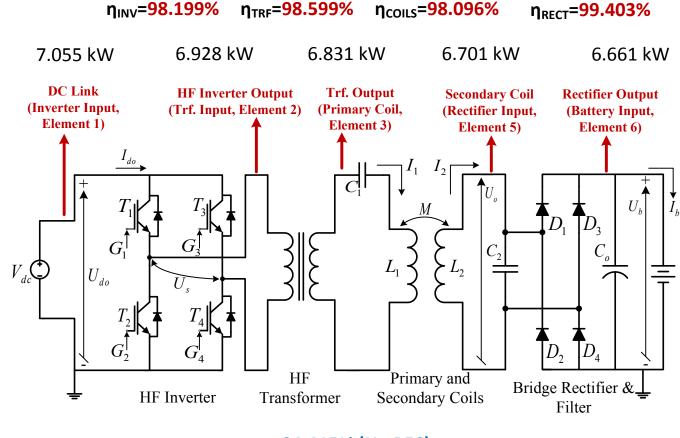


SOLUTION: MATCHED PRIMARY AND SECONDARY COILS



Static WPT Demonstration -6.6kW at ORNL – With Matched Coils

- Coil-to-coil efficiency: 94.17% to 98.1%.
- Other stages such as vehicle side rectifier and grid side inverter efficiency also improved due to the reduced reactive power that they had to handle earlier with poor power factor.



η_{DC-to-DC}=94.415% (No PFC)



Interoperability with Different Coils

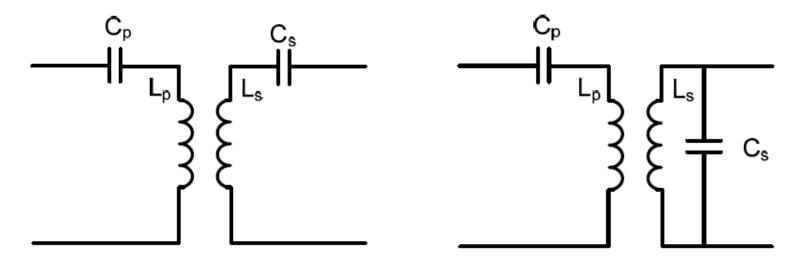
- SAE J2954 efficiency requirements
- Interoperable refers to the coils of different dimensions, types, and manufacturers.

	J2954 Proposed WPT Power Class					
	WPT1	WPT2	WPT3	WPT4		
Maximum AC <u>input</u> power	3.7kVA	7.7kVA	11.1kVA	22kVA		
Load power	~3-3.3kW	~6.6kW	~9.4kW	~18.7kW		
Minimum target efficiency with matched coils	>85%	>85%	TBD	TBD		
Minimum target efficiency with interoperable coils	>80%	>80%	TBD	TBD		



Progress Towards High Power > 20 kW: Resonant Tuning Configurations and Impact

Series-series (SS) and series-parallel (SP) configurations

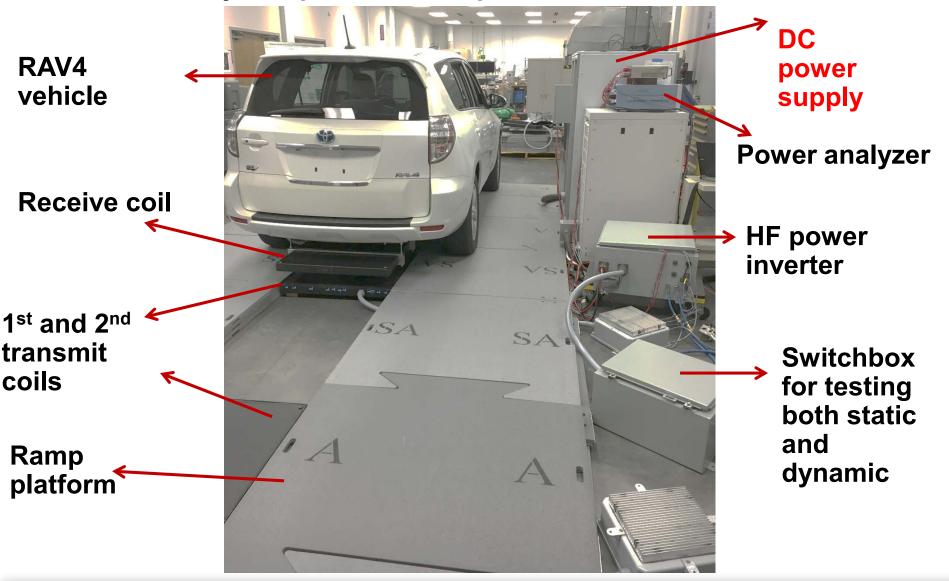


- SP is ideal for voltage driven vehicle side (vehicle side OBC, CHAdeMO needing voltage for start-up, etc.)
- SS can be used for direct battery connected systems.
- SS results in lower primary coil current → Less B-field and E-field, higher overall power rating without hitting limits of the system



Static WPT Test Setup – System Descriptions

Laboratory setup with RAV4 updated with Matched Coils

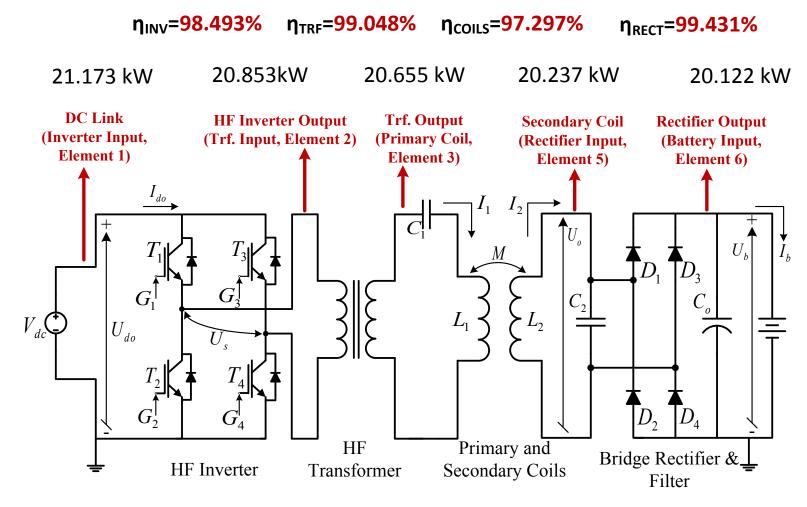


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Static WPT Demonstration <a>>20kW power transfer to RAV4

Power flow and power conversion stage efficiencies:



η_{DC-to-DC}=95.037% (No PFC)



Static WPT Demonstration >20kW power transfer to RAV4

Normal Mode	Peak Over 11 12 13 14 15 16 Strad Scaling 11 12 13 14 15 16 Trad AVG	Integ:Reset Line Filter Time::	YCKOGAWA ♦ PLL : ^{III} Error	Normal Mode		Peak Over 11 12 13 14 15 16 5Pd 11 12 13 14 15 16 Tr4	Scaling 🗮 Line Filto AVG 🚆 Freq Filto	er 🗮 🛛 Time	nteg: Reset YOKOGAWA ◆
& change items		PAGE	CF:3	🚳 & change iter	ns				PAGE CF:3
Element 1	Element 2 Element 3	Element 4 Element 5 Element 6 🚬	Element 1		Element 1	Element 2 Eleme	ent 3 Element 4	Element 5	Element 6
Urms [V] 424.76	384.25 300.32	376.12 380.95	U1 600V AUTO 1 100mA AUTO Sync Src: <mark>U3</mark>	Eff_INV [%]	98.493				2 1 1 100mA AUTO Sync Src:
Irms [A] 49.85	57.54 71.18	58.66 52.82 3	Element 2 U2 600V AUTO 2 100mA AUTO	Eff_TRFP [%]	99.048				Element 2 3 U2 600V AUTO 12 100mA AUTO
P [W] 21.173k	20.853k 20.655k	20.237k 20.122k 4	Sync Src 113	Eff_C2C [%]	97.297				4 Sync Src:
Q [var] -0.271k	-7.346k -5.506k	-8.790k -0.093k 5	Element 3 U3 600V (AUTO) 13 100mA (AUTO) Sync Src: 10	Eff_TRFS [%]					Element 3 5 U3 600V AUTO 13 100mA AUTO Sync Src:
S [VA] 21.174k	22.110k 21.376k	22.063k 20.122k	Element 4	Eff_RCT [%]	99.431				Element 4
λ [] 0.9999	0.9432 0.9663	0.9172 1.0000 7	U4 600V AUTO 4 100mA AUTO Sync Src: 113	Eff_Totl[%]	95.037				7 U4 600V AUTO 14 100mA AUTO Sync Src: 10
¢ [°] D0.74	D19.41 D14.93	D23.48 D0.26	Element 5 U5 600V AUTO 15 100mA AUTO Sync Src: U8	Eff_DCDC [%]	95.037				9 U5 600V AUTO 15 100mA AUTO
Cap_V [V] (1.0509k				P [W]	21.173k	20.853k 20	.655k	20.237k	20.122k Sync Src:
COIL_V[V] 1.0526k			Element 6 U6 600V AUTO 16 100mA AUTO Sync Src:	Urms [V]	424.76	384.25 30	0.32	376.12	Element 6 380.95 16 100mA Auro Sync Src:
		[Motor Spd 20V Trg 20V						Motor Spd 20V Trq 20V
Update 3158 (50msec)		2016	/02/03 05:06:46	Update 3158 (50msec)				2016/02/03 05:06:49

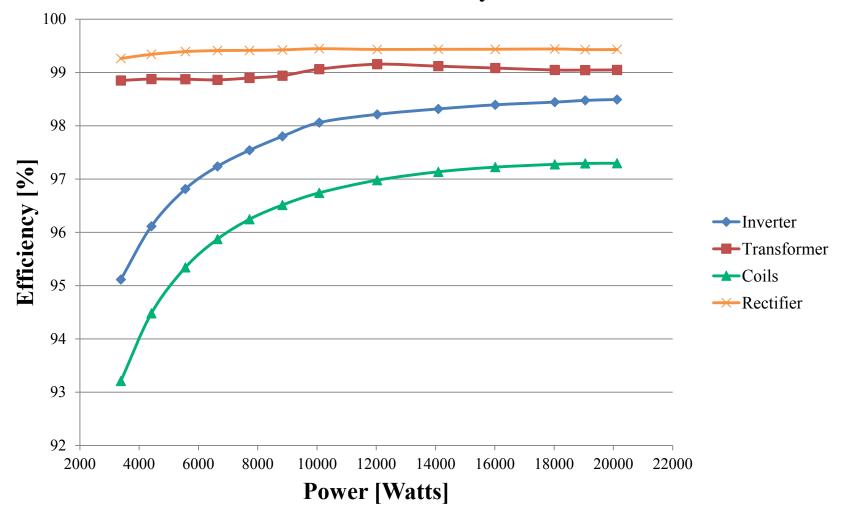
Power across each stages

Efficiency across power conversion stages



Progress Towards High Power: Comparisons (ii)

Power vs Efficiency 20kW





Higher Airgap Separation Test Results:

184mm airgap

• 10411111 a	iiyap				
Normal Mode Peak	105 06 Seal Scaling 💻 Line Filter 🗮 Time	Integ: Reset YCKOGAWA ♦ PLL : III Error	Airgap	DC-to-DC effi	ciency @14kW
& change items Element 1 Element 1		Element 6	162mm	95.16%	20/ reduction 20mm circon increase
Urms [V] 390.64 364.91	l 169.00 414.03	419.79 2 Sync Src: 10	184mm	93.83%	33% reduction 22mm airgap increase
Irms [A] 39.37 48.17	7 93.20 38.48	34.38 3 Element 2 34.38 3 12 600V AUTO 12 100mA AUTO		JJ.0J /0	3.14% reduction 22mm airgap
P [W] 15.379k 15.116	6k 14.938k 14.517k	14.430k 4 Sync Src:	206mm	90.69%	/ increase
Q [var] -0.214k -8.974	łk −4.995k −6.559k	-0.170k 5 U3 600V AUTO 13 100mA AUTO Sync Src: 10			
S [VA] 15.380k 17.575	9k 15.751k 15.930k	14.431k 6 Element 4 7 U4 600V AUTO			
λ [] 0.9999 0.8599	9 0.9484 0.9113	0.9999 8 44 100mA AUTO Sync Src: 10			
♥ [°] D0.80 D30.70	D D18.49 D24.31	D0.67 9 U5 600V AUTO 15 100mA AUTO	• 206	mm airgap	
Cap_V [V] 1.3761k		Sync Src:	Normal Mode	Peak Over	Integ: Reset YOKOGAWA 🔶
COIL_V[V] 689.99		U6 600V AUTO 6 100mA AUTO Sync Src: 100	😰 & change items	IIIZI3I4I5I6Ira AVG	B Line Filter IIme: PLL:001 Error FreqFilter PLC:005 PAGE CF:3
		Motor Spd 20V	Elen	nent 1 Element 2 Element 3	Element 4 Element 5 Element 6 1 U1 600V/AUTO 1 200mA/AUTO
				50.60 328.73 198.69	414.31 419.73 2 Sync Src:
Update 1834 (50msec)		2016/01/07 04:49:53		45.46 57.07 115.68	38.54 34.43 3 U2 600V AUTO
			P [W]	15.94k 15.49k 15.30k	14.53k 14.45k 4 Element 3
93.20A, more			Q [var]	-0.22k -10.58k -17.15k	-6.61k -0.17k 5 13 200mA auto 6 Sync Src:
increase airga	ip without		S [VA]	15.94k 18.76k 22.99k	15.97k 14.45k Element 4 7 U4 600V Auro
hitting the limi	t		λ [] 0	.9999 0.8259 0.6658	0.9102 0.9999 8 4 200m Auro
C	115.68A even	at the	¢ [°]	D0.79 D34.32 D48.25	D24.47 D0.69 Element 5 U5 600V Martin 15 200mA Martin
			Cap_V [V] 1	.7079k	Sync Sra:
	worst case, m		COIL_V[V] 6	91.31	U6 600¥ AUTO 16 200mA AUTO
	to increase ai	•			Sync Src:
	without hitting	the limit			Spd 20V Trq 20V
			Update 2397 (50m	isec)	2016/01/07 05:41:38

21 ORNL Wireless Charging Technology: Phase #3 Progress and Demonstration

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Step-by-Step Manual Testing for D-WPT

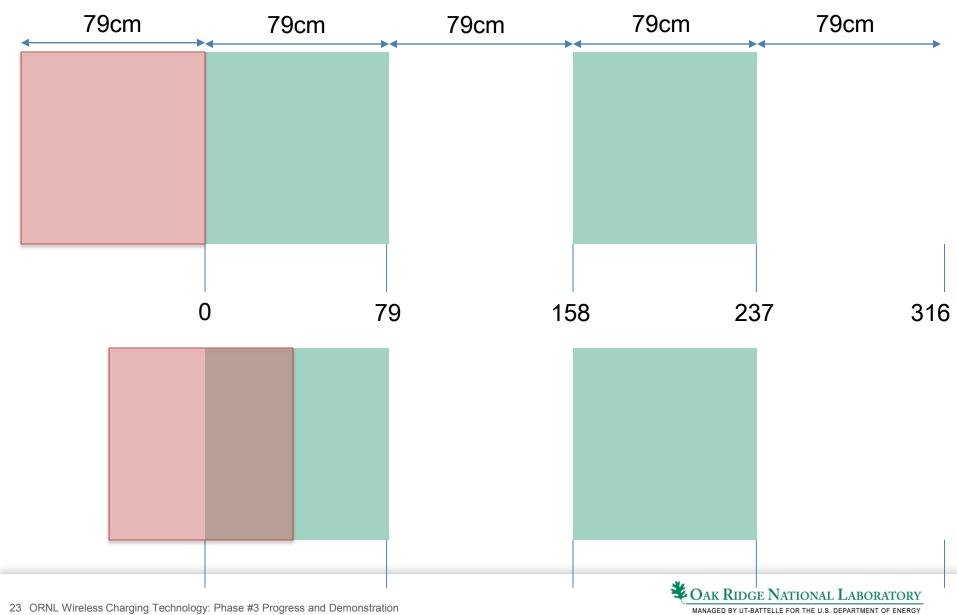
• Step by step manual dynamic WPT experiment and data collection



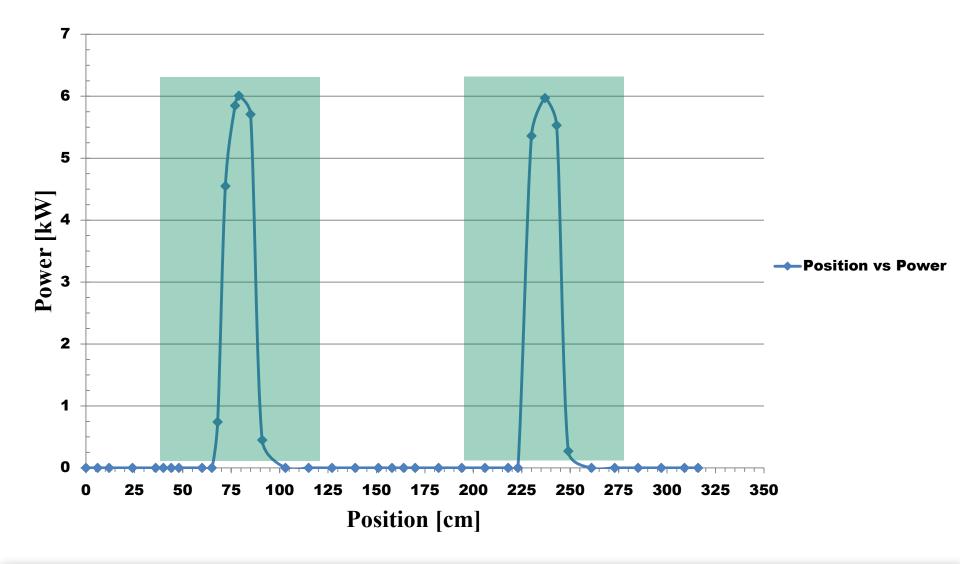




Lab test setup for tests:



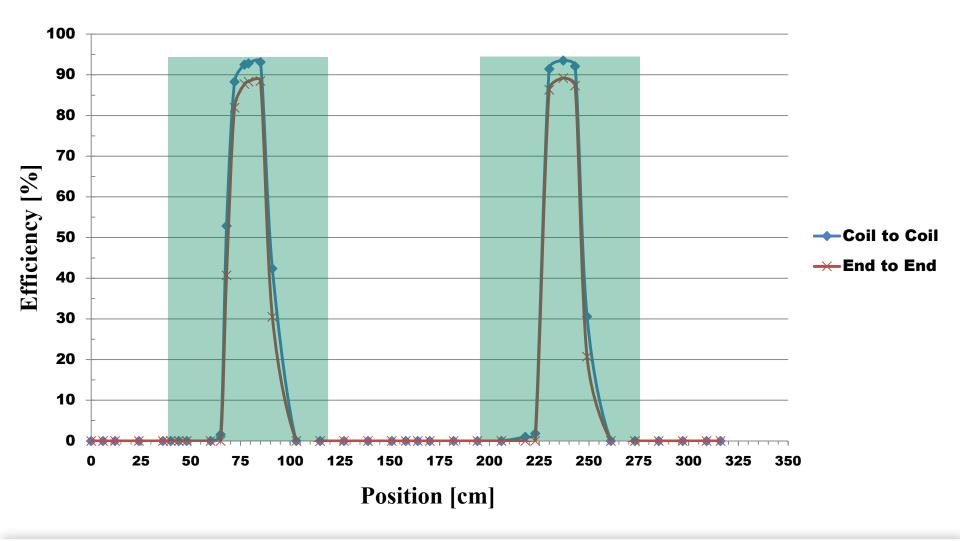
Lab test results – Series-series Tuning configuration:



Solar Ridge National Laboratory

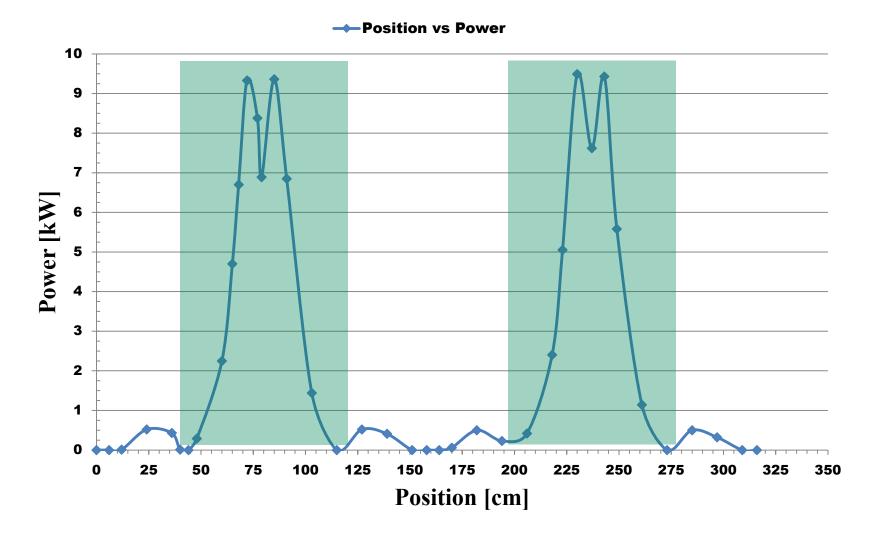
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Lab test results – Series-series tuning configuration:



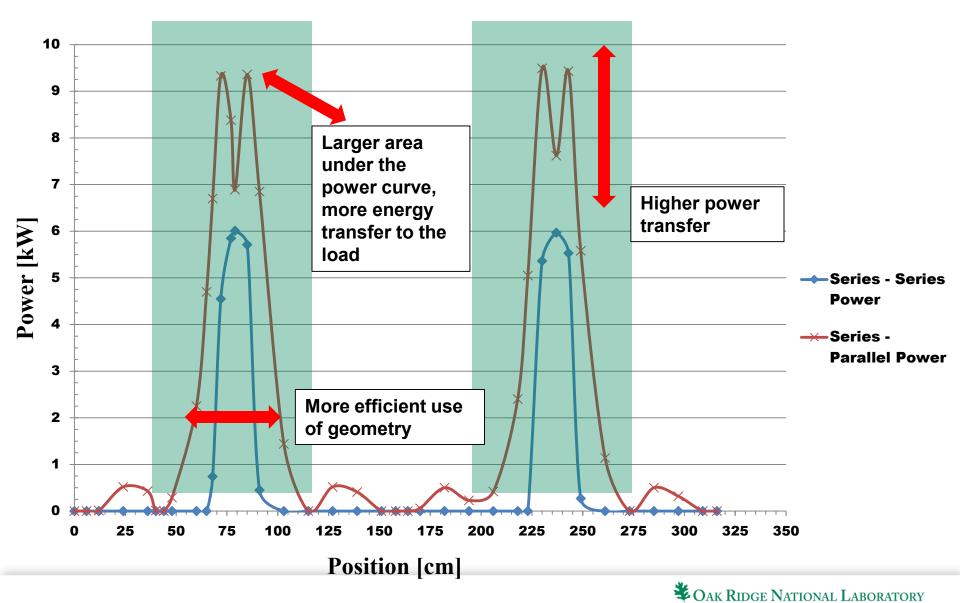


• Lab test results – Series-parallel Tuning configuration:



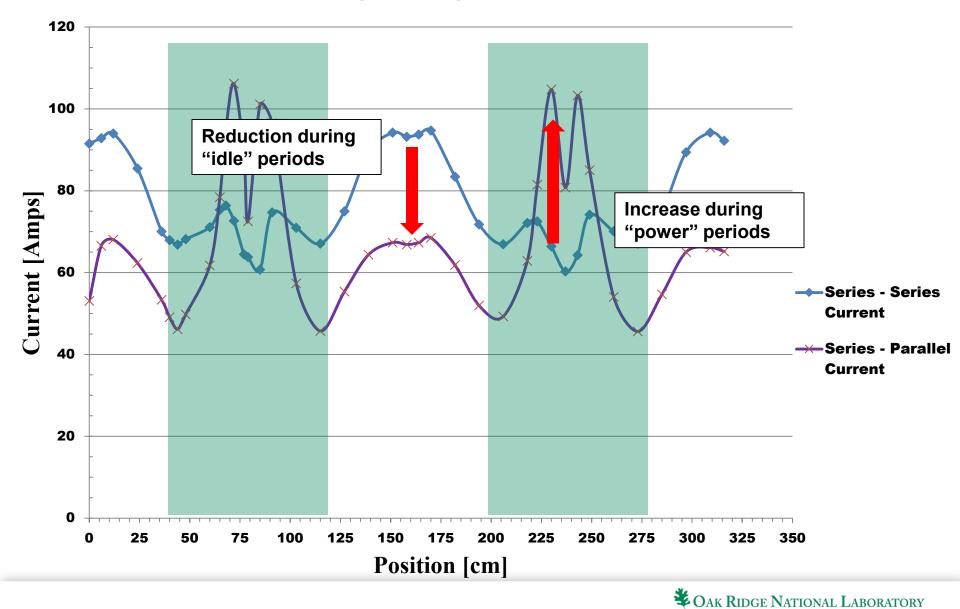


Lab test results –Tuning configuration comparisons:



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Lab test results –Tuning configuration comparisons:

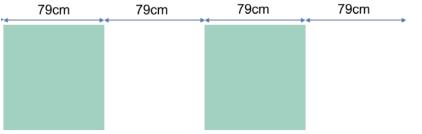


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Dynamic WPT Demonstration: Energy Transfer Discussion

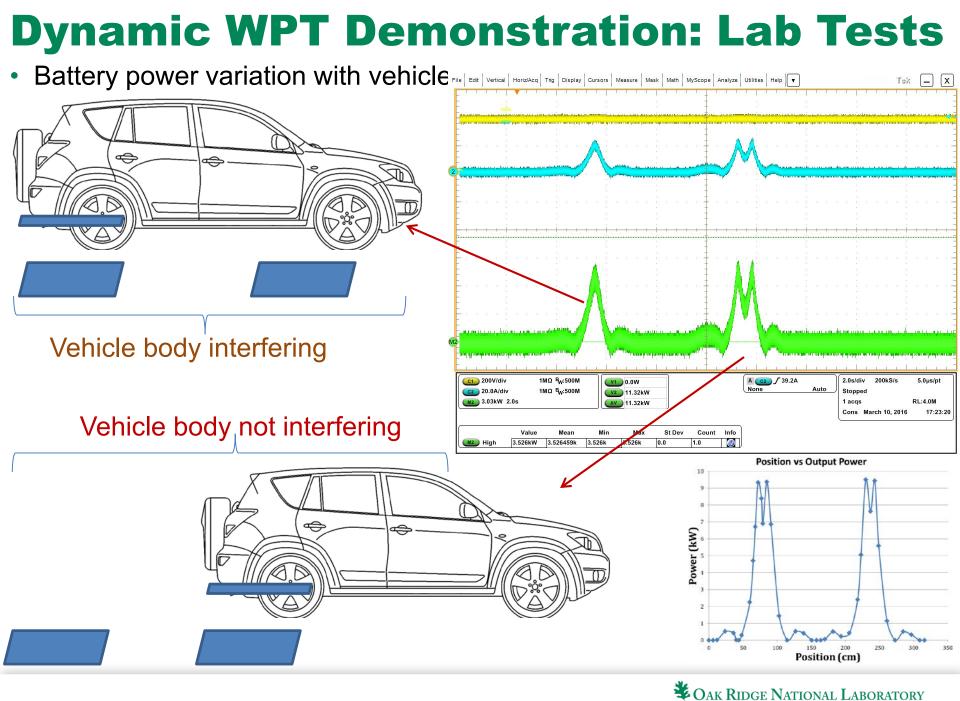
- Energy transfer: Time integral of power vs. time curve.
- Power vs. time curve is directly related to the power vs. position curve if speed is constant.

$$E = \int_0^t P(t)dt$$



- 50 miles per hour \rightarrow 2235 cm per seconds
- It takes 141ms to complete the track of 2 coils with a total length of 316cm
- For series-series tuning E1=<u>97.2 Watt-seconds</u> (joules) (time integral of 'power vs. time curve')
- For series-parallel tuning E2=<u>281.08 Watt-seconds</u> (joules) → <u>Three</u> <u>times more energy transfer to the vehicle battery</u>





30 ORNL Wireless Charging Technology: Phase #3 Progress and Demonstration

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Vehicle body Interference Discussions

Lab test results –with the vehicle





Dual motor \checkmark mechanical support. Thick steel plate.

Toyota RAV4 vehicle frame to protect battery pack on the floorboard (Tesla designed).



Tesla designed dual motor traction drive system

Dual motor enclosure and frame housing.





Dynamic WPT Demonstration: Energy Transfer Discussion

- Assuming a typical mid-size sedan vehicle, 0.3kWh (300Wh) is needed to drive 1 mile (1609 meters). Track length with two coils: 0.316 meters
- Therefore:

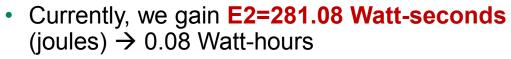
 $Tavel\ distance\ worth\ energy\ captured\ from\ two\ coils =$

$$0.316 [meters] = E [Watt - hours] \times \frac{1609 [meters]}{300 [Watt - hours]}$$

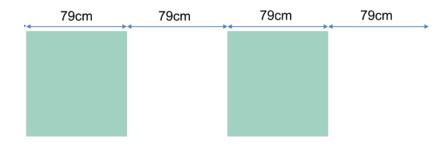
$$E = 0.316 [meters] \times \frac{300 [Watt - hours]}{1609 [meters]} = 0.06 Watt - hours$$

 $E = \int_{a}^{b} P(t)dt$

Floctricity



- 75% of a highway should we covered with coils with 9.28kW peak power
- With 100kW power transfer, only 7.5% of the roadway should be WPT installed.





Response to Previous Year Reviewer's Comments

- Q1) One of the reviewers stated that there appears to be a good level of collaboration in this
 project; however, the reviewer wondered why INL has not been brought into this project with their
 wireless charging test setup. The reviewer asked if this is something that ORNL plans going
 forward.
- A1) In fact, an independent laboratory testing, to be performed by INL, was included in the program objectives. In October 2015, INL received a Toyota RAV4 vehicle with ORNL, including a grid side unit. INL conducted extensive testing of the system and evaluated the performance under various operating conditions (misalignment, airgap, battery voltage, input AC voltage, various power levels, etc.). INL testing helped ORNL evaluate the system characteristics and ORNL was able to improve system efficiency and maximum power substantially.
- Q2) The reviewer pointed out that the technical accomplishments were being met and that the project was on track. One thing that was not clear was whether the SAE decision to go with a different frequency would negatively impact this project going forward and whether Evatran would abandon the technology in favor of one that adheres to the SAE standard. The reviewer suggested that providing evidence of a contingency plan for this situation and a discussion of what the reasons are for the SAE decision would be good additions to future presentations.
- A2) ORNL is currently working on wide bandgap device technologies what will meet the 85kHz center frequency as indicated in the SAE J2954 TIR. Currently, ORNL designed SiC power converter is one of the very few developments that can meet high frequency requirements while still allowing to transfer high power (WPT Level-2) at target efficiencies. The inverter was tested at 10kW at 85kHz with an efficiency of >98%.



Proposed Future Work

- FY2016 (remainder)
 - Software improvements in the system to further improve the vehicle agnostic (interoperable) operation of the system
 - Complete additional testing to demonstrate system operation that is independent of the battery voltage, state-of-charge, and reference (target) power to the vehicle battery pack.
 - Submit additional technical papers for journals and upcoming conferences.



Conclusions for Static WPT Development and Testing

- WPT system explained including functional diagram and test setup
- Matched / interoperable coil impact on maximum power and efficiency
- SS and SP tuning impact
- Progress towards high power WPT
- Summary of FOA requirements and current status

	FOA Project Requirement	Current Status
Airgap:	160mm	162mm nominal, also tested 184 and 206mm
Efficiency	85%	~92-93% (with estimated PFC eff.)
Maximum load power	6.6kW	20.2kW



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