

2011 DOE Vehicle Technologies KIVA-Development

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Los Alamos National Laboratory
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LA-UR-11-10120

Project ID # **ACE014**

This presentation does not contain any proprietary, confidential, or otherwise restricted information

Timeline

- 10/01/09
- 09/01/13
- 40% complete

Budget

- Total project funding to date:
 - 1,140K
 - Contractor share 30%
- Funding received in FY10
 - 580K
 - Funding for FY11 – 660K
 - Received only 1/3
 - Continuing Resolution restricting ability to meet milestones and progress

Barriers

- Improve understanding of the fundamentals of fuel injection, fuel-air mixing, thermodynamic combustion losses, and in-cylinder combustion/ emission formation processes over a range of combustion temperature for regimes of interest by adequate capability to accurately simulate these processes
- Engine efficiency improvement and engine-out emissions reduction
- Minimization of engine technology development

Partners

- Iowa State University - Dr. Song-Charng Kong (under funded)
- University of Nevada, Las Vegas - Dr. Darrell W. Pepper (not yet contracted FY 11)
- University of Purdue, Calumet - Dr. Xiuling Wang (under funded)
- University of New Mexico- Dr. Juan Heinrich (FY 11 - not yet contracted)

Objectives

- **Robust, Accurate Algorithms in a Modular setting –**
 - **Relevance to accurately predicting engine processes to enable better understanding of, flow, thermodynamics, sprays, etc....**
 - Developing more robust and accurate algorithms for helping to understand better combustion processes in internal engines
 - Providing a better mainstay tool for improving engine efficiencies and help in reducing undesirable combustion products.
 - Newer and mathematically rigorous algorithms will allow KIVA to meet the needs of future and current combustion modelers and designers.
 - Developing Fractional Step (PCS) Petrov-Galerkin (P-G) and Characteristic-Based Split (CBS) *hp*-adaptive finite element method
 - Conjugate Heat Transfer for providing more accurate prediction in wall-film and its effects on combustion and emissions under PCCI conditions with strong wall impingement. Providing accurate boundary conditions.
- **Easier and quicker grid generation**
 - **Relevant to minimizing of engine technology development**
 - Cut-Cell grid implementation: CAD to CFD
 - Cut-cell output to KIVA-4 via Cubit and Cubit to KIVA converter.

Milestones for FY 10- FY11

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- 06/09- **Started Researching** Fractional Step CBS method – developed some research coding and altering/combining with existing Projection code and *h*-adaptive algorithms.
- 09/09 – **2D and 3D P-G Fractional Step** (PCS/CBS) Finite Element Algorithm Developed (mathematics, engineering documents and evaluation).
- 01/10 – ***h*-adaptive** grid technique/algorithm implement in PCS/CBS-FEM method for 2D
- 02/10 – ***h*-adaptive** grid technique/algorithm implement in PCS/CBS-FEM method for 3D
- 02/10 – ***hp*-adaptive FEM Algorithm & Framework**: continued development and changes.
- 02/10 thru 09/10 –
 - Successful at meeting standard benchmark** problems in the incompressible regime using CBS Fractional Step (PCS) and P-G stabilization without CBS stabilization.
- 04/10 – **New algorithm** for **Cut-Cell** grid generation started – more robust algorithm.
- 05/10 – **Multi-Species Transport** testing in PCS/CBS-FEM algorithm.
- 09/10 – **2D and 3D Characteristic-based Split** (CBS) stabilization extended to turbulence closure routines. Continue debugging CBS and combination of CBS and PG capabilities.
- 10/10 – **P-G found to be more flexible** than CBS stabilization via benchmark comparisons.
- 12/10 – **Start looking into Runge-Kutta** method for 2nd order-in-time in P-G only Fractional Step.
- 12/10 – **Benchmark tests of PCS and CBS** and begin comparing results.
 - Find CBS a bit less flexible the P-G but, does provide good solution, and can be used with P-G.
- 12/10 – Inserting **PCS/CBS** algorithm/coding into ***hp*-adaptive Framework**.
- 01/11 – **FY11 Engineering documentation** and precise algorithm details.
- 02/11 – Continue working the **PCS/CBS** method in the **compressible flow** regimes.
- 02/11 – **Discussions with Sandia on Cut-cell** (our algorithm) & incorporation into **Cubit** software.

- Approach for Developing Robust and Accurate Numerical Simulation Code:
 - Computational Physics
 - Understanding of the physical processes to be modeled
 - Assumptions inherent in any particular model
 - Ability of the chosen method, the mathematical formulation, and its discretization to model the physical system to within a desired accuracy.
 - The ability of the models to meet and or adjust to users' requirements – modularity, documentation.
 - The ability of the discretization to meet and or adjust to the changing needs of the users.
 - Validation and Verification (V&V) – meeting requirements and data.
 - Effective modeling employs good software engineering practices.

Development Approach and Milestones

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- Approach for Robust and Accurate Numerical Simulation:
 - Development Process
 - Understanding of the physical processes to be modeled
 - Mathematical representations and evaluation of appropriate methods and models.
 - Guiding engineering documents
 - Assumptions inherent in particular model and methods
 - Ability of hp-adaptive PCS/CBS method, the mathematical formulation, and its discretization to model the physical system to within a desired accuracy.
 - The ability of the models to meet and or adjust to users' requirements – chose
 - The ability of the discretization to meet and or adjust to the changing needs of the users.
 - Effective modeling employs good software engineering practices.
 - Modularity, Documentation, Levelized (under-the-hood)
 - Validation and Verification (V&V) – meeting requirements and data.
 - Verification via known algorithm substitution
 - Validation and development process
 - Benchmark Problems that exercise all code in all flow regimes

- Developing *hp*-adaptive PCS/CBS FEM Discretization for:
Accurate and Robust Turbulence Reactive Flow Modeling – Combustion Modeling
- **2-D and 3-D PCS/CBS *h*-adaptive FEM codes are coded:**
 - Benefit of Eulerian system with 2nd order-in-time algorithm
 - Performed without large system of linear equations to solve!
 - CBS or Petrov-Galerkin Stabilization (P-G) having 3rd order spatial accuracy
 - Numerical dispersion precisely measured and removed prior to solution advancement.
 - Various choices of Stabilizing Modes:
 - P-G with CBS for **2nd order-in-time** or use CBS alone for **2nd order-in-time**
 - 1 pressure solve per time step : Semi-implicit or an Explicit modality.
 - Equal-order: same basis for pressure and momentum (if desired).
 - *h*-adaptive with Residual error & Gradient control (incorporated FY 09).
 - *k- ω* turbulence model FY-09 & FY-10
 - *k- ϵ* blended low Reynolds (Wang, Carrington, Pepper 2009) .
 - New wall function system for both 2D and 3D - compressible (variable density in FY11).
 - PCG Solver & in-situ stationary preconditioning (FY 10)
 - New MAKE system (FY10).
 - Stochastic particle model - now porting KIVA-4 model to FEM method FY11/12.
 - Verification complete
 - Via known algorithm substitution and benchmark problems solution
 - Validation and continued development and error/bug removal via
 - Benchmarks Problems

- Conjugate Heat Transfer (CHT)
 - Motivation
 - Extend KIVA-4 capability to predict heat conduction in solids.
 - Use KIVA-4 to perform simultaneous simulation of in-cylinder processes and heat conduction in mechanical components.
 - Expected outcome
 - Prediction of combustion chamber wall temperature distribution.
 - More accurate prediction of wall film and its effects on combustion and emissions under PCCI conditions with strong wall impingement.
 - Approach
 - Modify KIVA-4 for heat conduction calculation in solid.
 - Extend the computational domain to include both fluid and solid domains.
 - Perform integrated thermo-fluids modeling in one simulation using the same code.
 - Applicable energy equation is solved for temperature distribution in solids

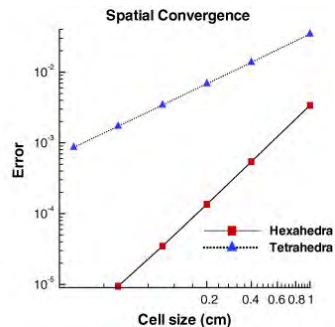
Why Do We Need New Method? Accuracy & Robustness

KIVA-4 Spatial Convergence vs. FEM on **Regular** Grids

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Merit Review

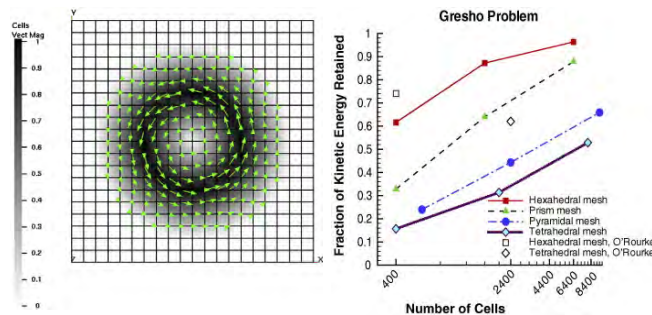
KIVA-4*

1-D diffusion



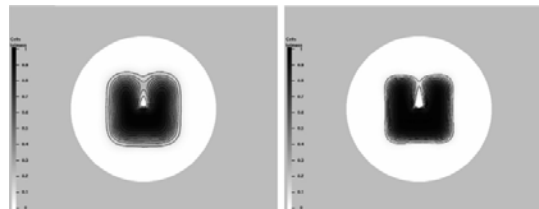
Slope for tets ~ 1

Gresho momentum flux



*used with permission from Dave Torres.

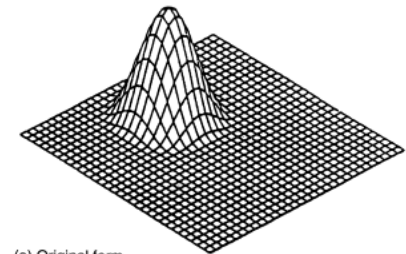
Rotating notch



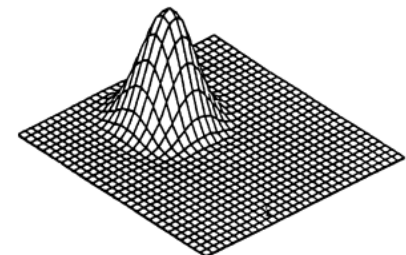
6,000 prisms 88,000 prisms

FEM- CBS**

Rotating Cosine hill
similar to rotating notch



(a) Original form



(b) Form after one revolution using consistent M matrix

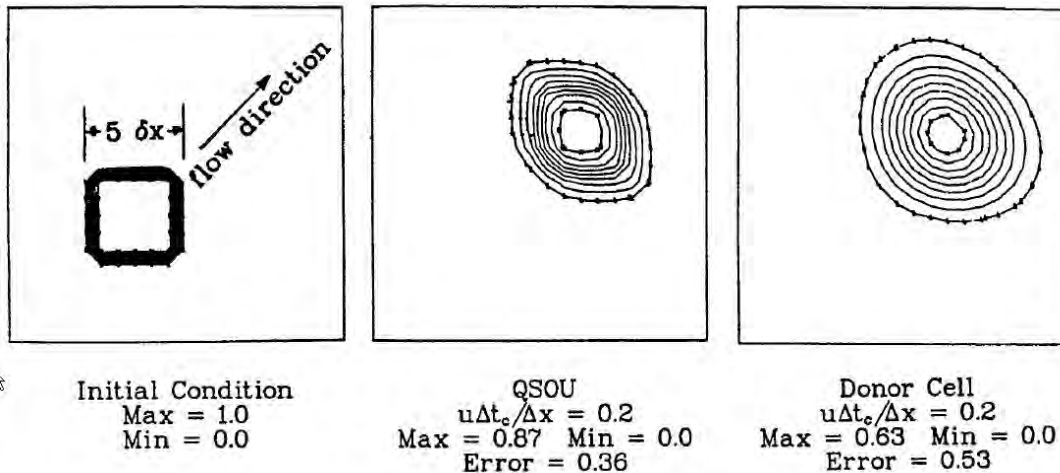
~225 cells

**used with permission from Elsevier Publishing-
Finite Element Method for Fluid Dynamics (6th
Edition) , Zienkiewicz, O.C.; Taylor, R.L.; Nithiarasu,
P. © 2005 Elsevier

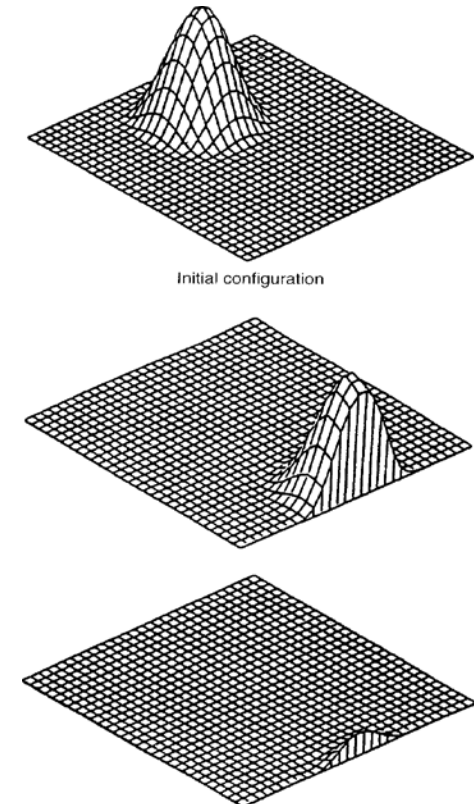
Why Do We Need New Method? Accuracy & Robustness

Eulerian advection: Current KIVA vs. FEM on **Regular** Grids

Current KIVA advective Flux*



CBS-FEM Advection**



Phase C **advective flux** is **very diffusive**

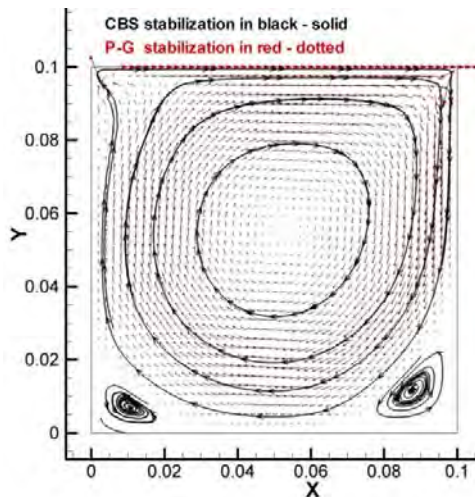
*from – KIVA-II manual: A Computer Program for Chemically Reacting Flows with Sprays, LA-11560-MS, Los Alamos Scientific Report, 1989.

** used with permission from Elsevier Publishing.
from - Finite Element Method for Fluid Dynamics (6th Edition) ,
Zienkiewicz, O.C.; Taylor, R.L.; Nithiarasu, P. © 2005 Elsevier

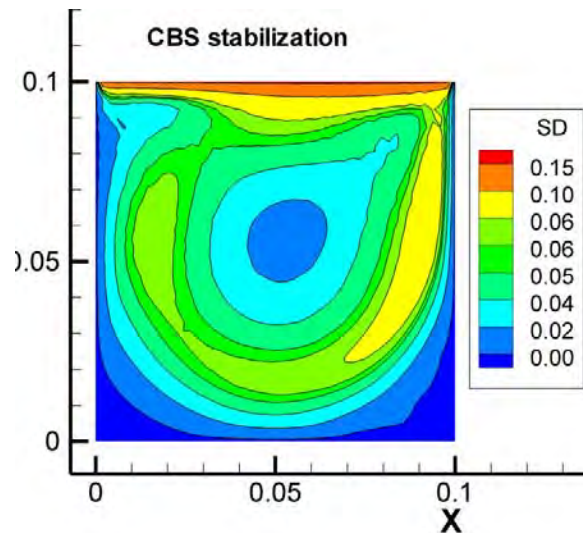
Advection is **nearly exact!**
Added benefit of Eulerian Frame
along with 2nd order-in-time without
large linear equations to solve.

Validation of 2-D Fractional Step – FEM

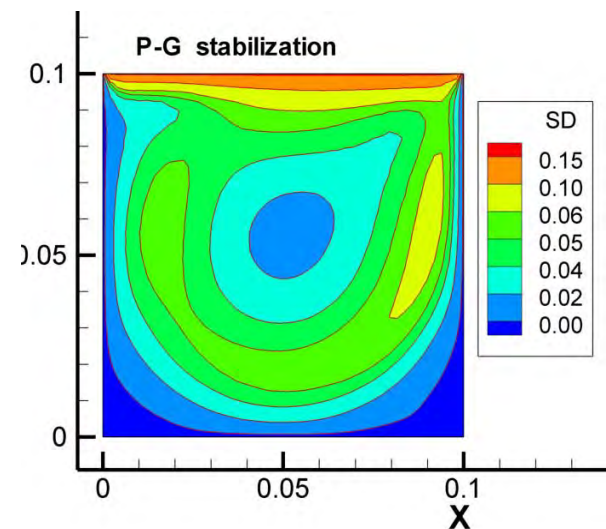
- Driven Cavity Benchmark – $Re = 1000$
 - Semi-implicit solve – pressure Poisson equation
 - **KIVA-4 published solution shows ~45,000 cells** for low Mach equations, an order magnitude larger than PCS or CBS FEM!
 - Characteristic vs. P-G :
 - P-G is more flexible, has good adjustment of element size h_e
 - Characteristic has 2nd O in time inherent in scheme
 - Adaptation at Pressure singularity in upper corners really helps solution



Grid 40x50



Characteristic stabilization

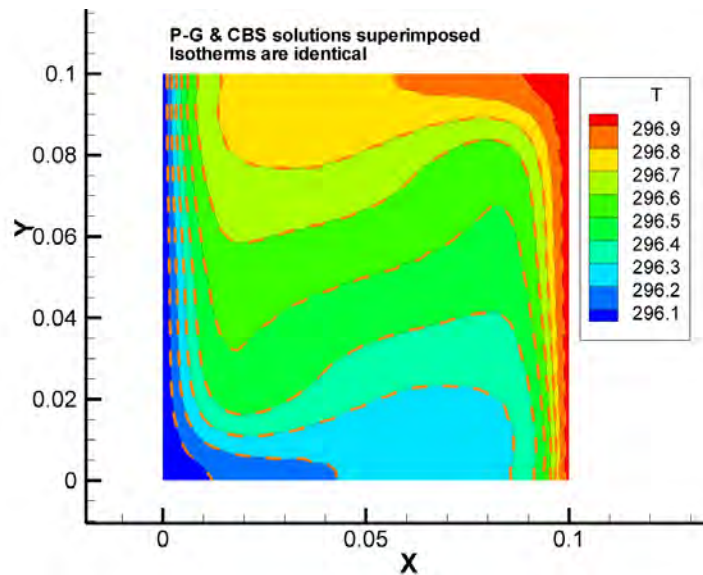


P-G stabilization

Validation of 2-D Characteristic-Based Split – FEM

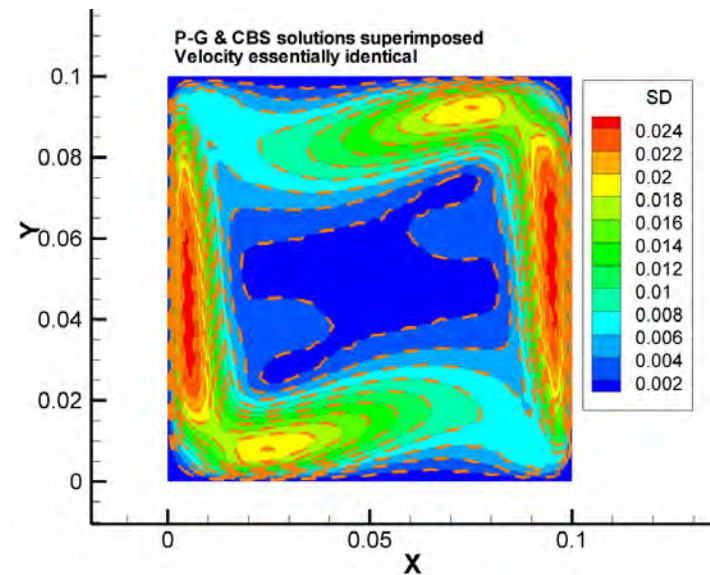
- Slightly compressible low speed flow.
- Differentially Heated Cavity - $Ra = 1.0e06$.
- Pressure Poisson matrix solved.
- Identical results between CBS and P-G stabilization
 - Source Term (*Boussinesq approximation*) helps 1st order –in-time scheme be as accurate as 2nd order CBS method.

2 solutions: P-G and CBS stabilization



Isotherms

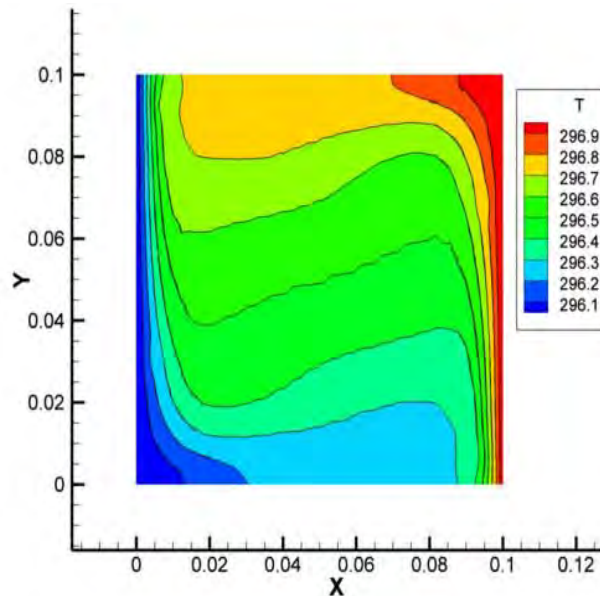
40x50 Grid



Isotachs

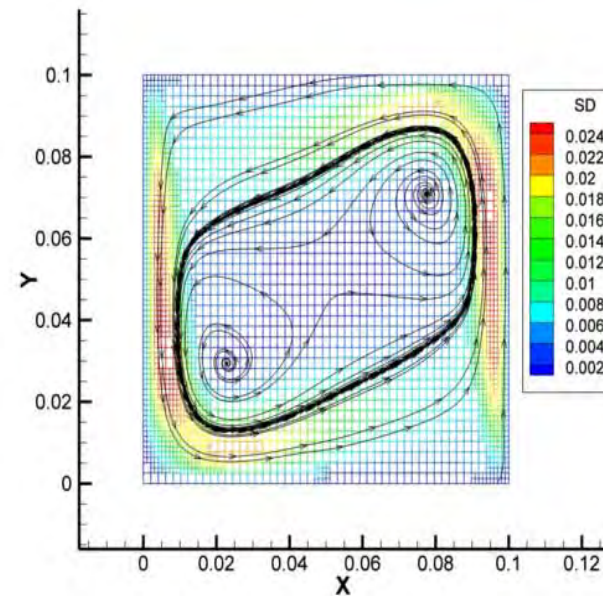
Validation of 2-D h -adaptive – PG PCS FEM

- Slightly compressible low speed flow.
- Differentially Heated Cavity - $Ra = 1.0e06$.
- Pressure explicit mode.
- P-G stabilization



Isotherms

Adapted 40x50 Grid

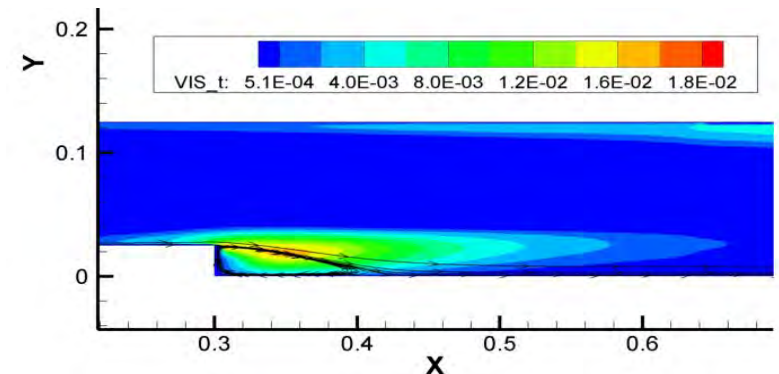
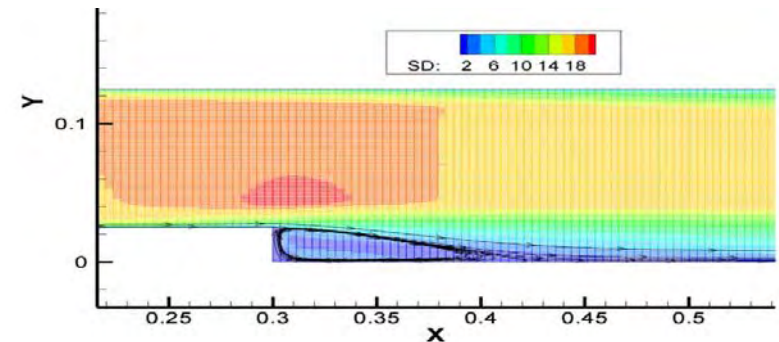
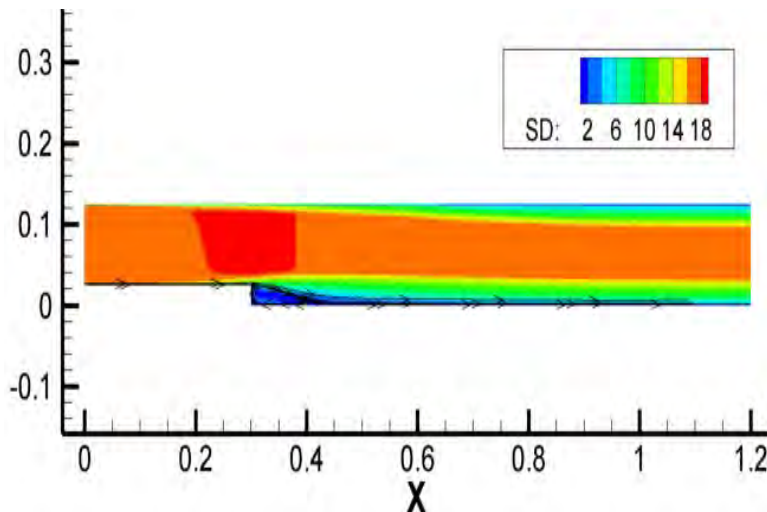


Isotachs

CBS/PG *h*-adaptive Validation

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- Turbulent convective flow over a backward-facing step
 - (current KIVA can't do this problem well).
- $Re=28,000$, inflow is 17m/s (Mach number ~ 0.05) matches data.
 - Lower velocity in a typical internal combustion engine.
- 2 species at inlet with different mass fractions, both are air
 - multi-species testing.
- 1 specie at $t=0$.
 - Combined CBS and P-G stabilization
 - $k-\omega$ closure model
 - currently recirculation $\sim 6.0h$

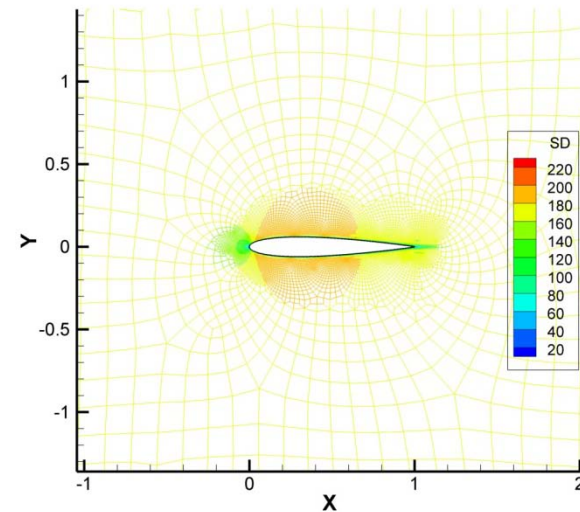
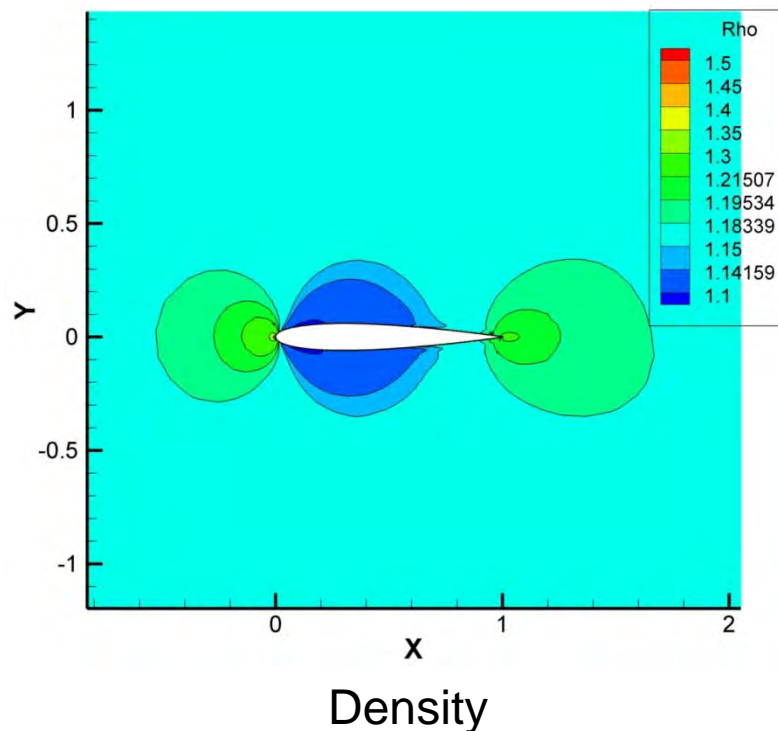


Subsonic flow regime

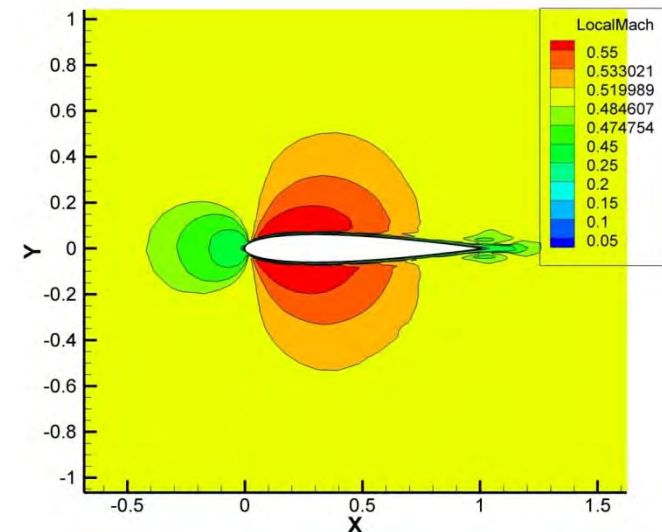
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- Time dependent solution
 - CBS and P-G combined system.
 - Multi-species testing, 2 species at inlet.

NACA 0012 airfoil test
Mach = 0.5 & $\alpha = 0$



~8000 cells and nodes – adapted on boundary

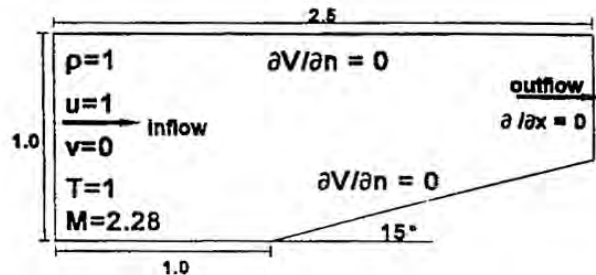


Local Mach Number

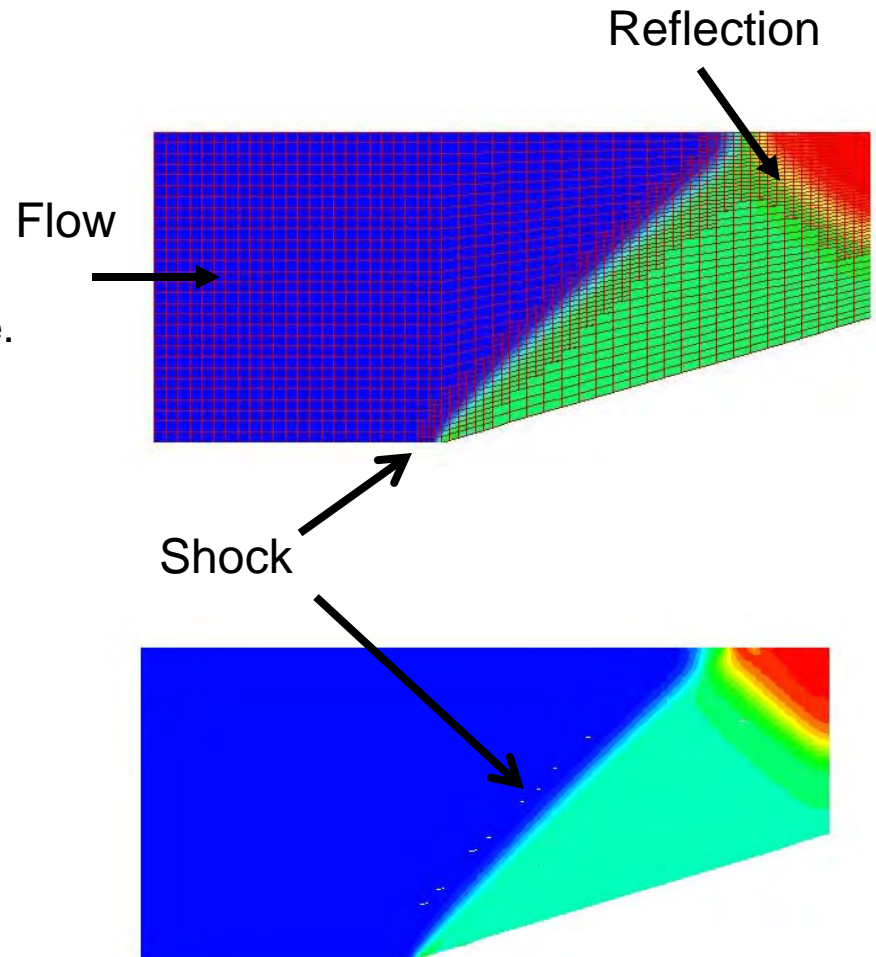
Density Contour on a Planar 15° Ramp at M=2.28

- 15° compression ramp
- h -adaptive P-G FEM
 - Explicit scheme with Runge-Kutta 2
- Time dependent solution
 - Our research code identical to CBS system in explicit mode.

Mach = 2.28 at inlet



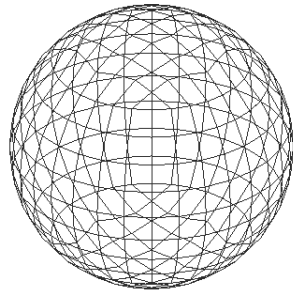
Boundary
Conditions



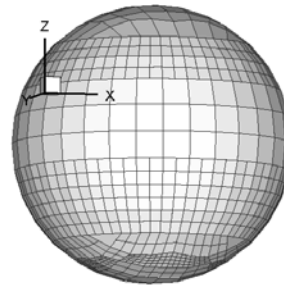
Natural Convection in a Differentially Heated Sphere

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Merit Review

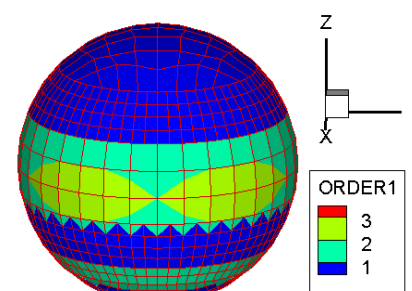
hp-adaptive FEM*



(a) initial mesh



(b) intermediate
h-adaptive mesh



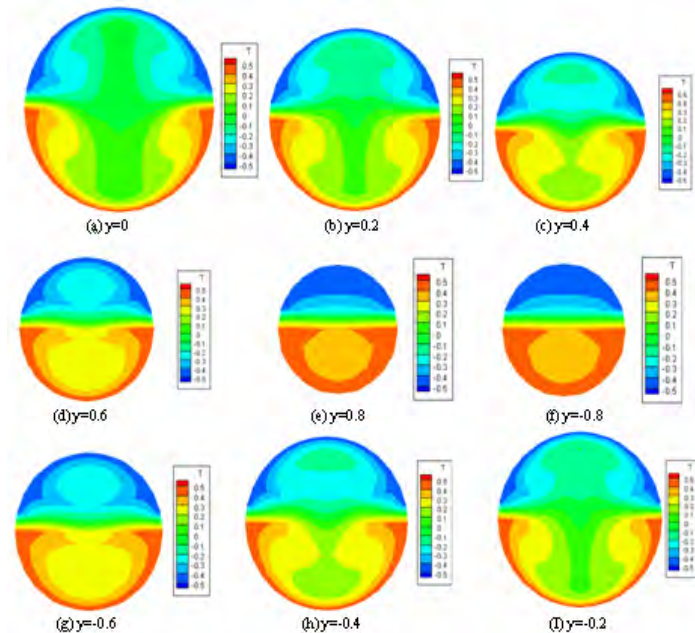
(c) final *hp*-adaptive mesh

$Ra=10^4$

- Demonstrating Solver Capability
- Truly curved and complex domains

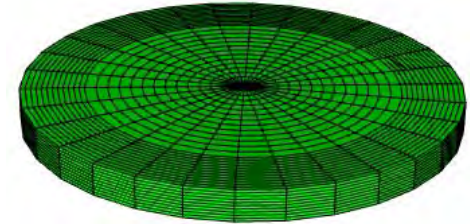
2-D planar isotherms at $-1 \leq R \leq 1$
-0.8, -0.6, -0.4, -0.2, 0.0, 0.2, 0.4, 0.6, 0.8
along major axis in x-z planes

*used with permission from Wang, X. and Pepper, D. W.

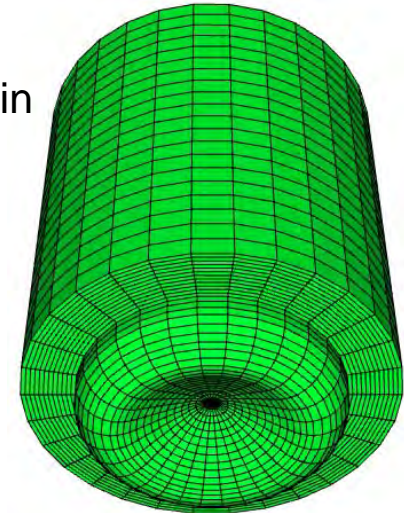


- Caterpillar engine cases
- Initial conditions for interfaces
 - $T_{\text{piston}}=550$ K
 - $T_{\text{head}}=523$ K
- Boundary conditions
 - $T_{\text{piston}}=500$ K
 - $T_{\text{head}}=400$ K
 - $T_{\text{wall}}=433$ K
- Spray conditions
 - $t_{\text{inj}}=-7.0$ CA, $\text{inj_dur}=19.75$ CAD

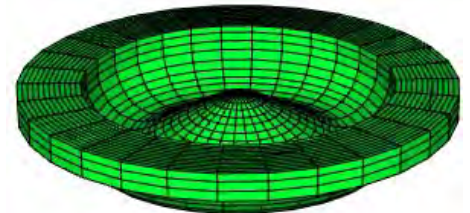
Head



Gas domain



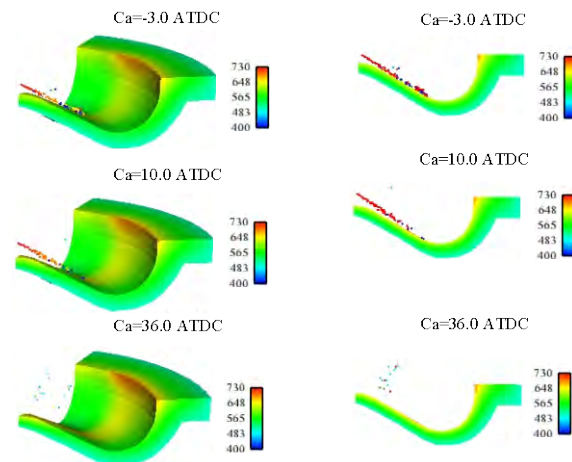
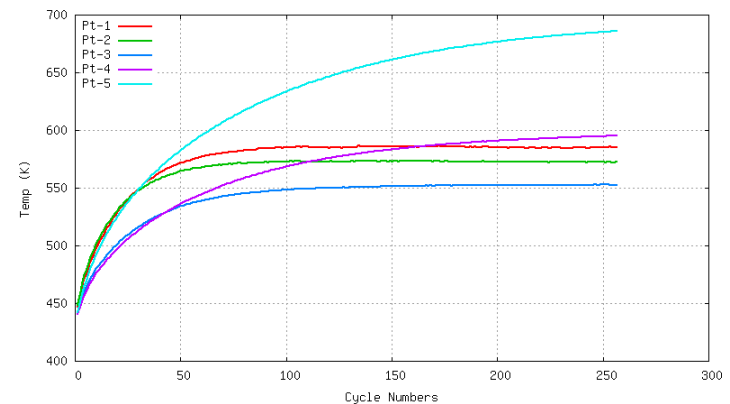
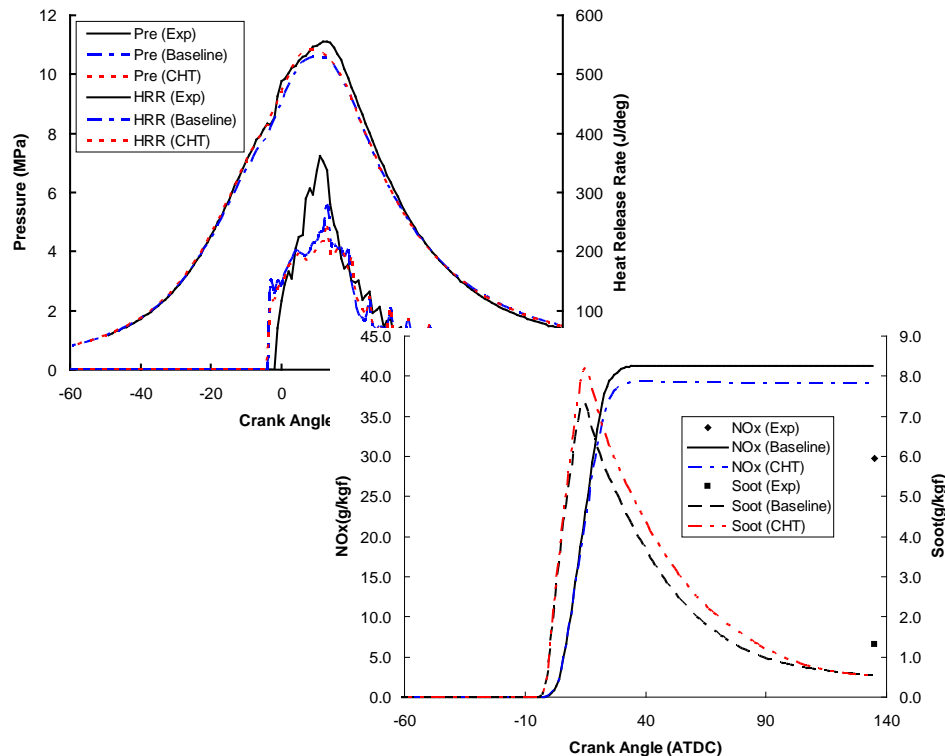
Piston



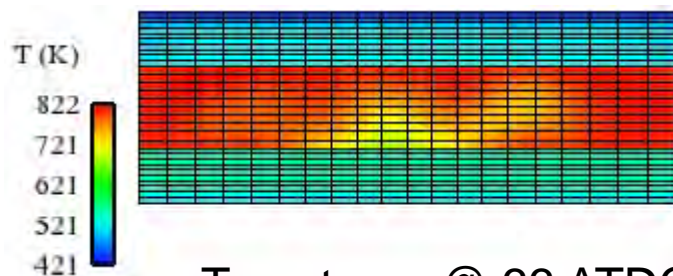
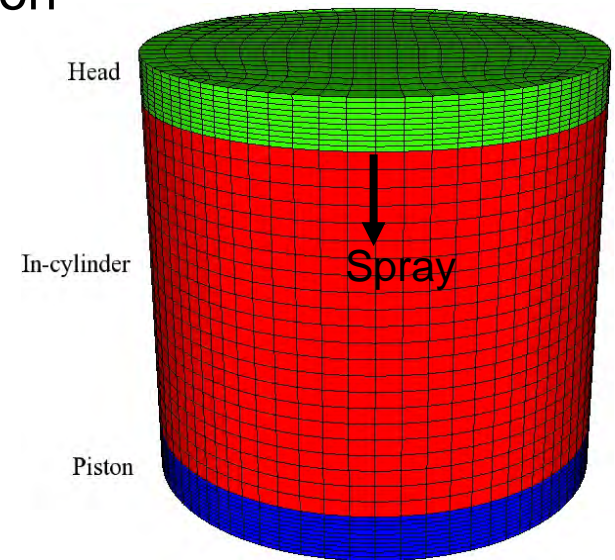
CHT - Cat Engine Test Results

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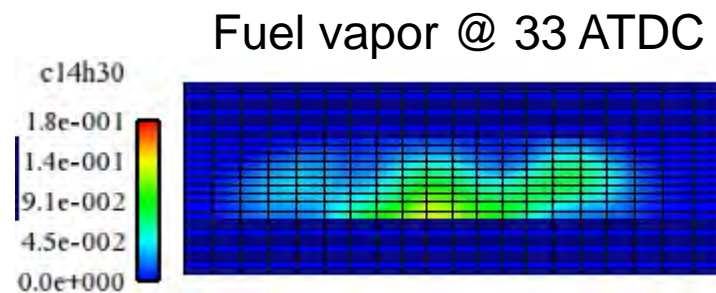
- Overall combustion and emissions predictions are similar to the baseline case using uniform surface temperatures.
 - In general users are good at specify temperature and making adjustments in the models to produce good results on known systems.
- Nonetheless, CHT is able to predict the surface T distribution (thermal loading) in the combustion chamber.
 - More predictive modeling capability.



- The code can run for both conventional mesh and CHT mesh
- CHT model validated via known analytic solution
 - Flat piston and cylinder head
 - Initial conditions for interfaces
 - $T_{\text{piston}}=550\text{ K}$; $T_{\text{head}}=523\text{ K}$
 - Boundary conditions
 - $T_{\text{piston}}=500\text{ K}$; $T_{\text{head}}=400\text{ K}$
 - Spray conditions
 - $t_{\text{inj}}=-9.0\text{ CA}$, $\text{inj_dur}=19.75\text{ CAD}$
 - $m_f=28\text{ mg}$



T contours @ 33 ATDC



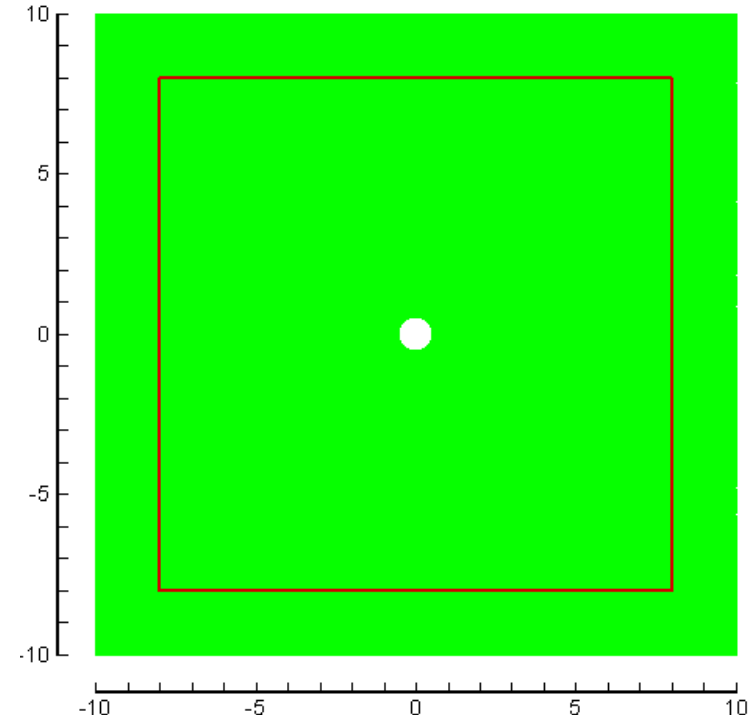
Fuel vapor @ 33 ATDC

- LLNL collaborating
 - providing great feedback and reporting on KIVA-4mpi
- Iowa State University
 - Conjugate Heat Transfer in KIVA-4 and KIVA-4mpi
 - Song-Charng Kong & GRA and Postdoc.
- Purdue, Calumet
 - *hp*-Adaptive FEM with Characteristic-Based Split (CBS)
 - Xiuling Wang (Purdue) and GRA
- University of Nevada, Las Vegas
 - *hp*-Adaptive FEM with Characteristic-Based Split (CBS)
 - Darrell Pepper (UNLV) and GRA.
- University of New Mexico
 - Moving Immersed Body and Boundaries Algorithm Development
 - Juan Heinrich and Graduate Student

- PCS/CBS-FEM
 - Test cases: finish tests (LANL & Purdue)
 - Simple unit, various benchmark problems and more complex domains too/
 - Make rigorous comparisons to data and analytics.
 - Publish results in peer reviewed articles.
 - Develop KIVA type I/O and interfacing.
 - Incorporate the injection/spray model and reactive chemistry coding.
 - Overset Grid method for moving parts. Moving grid – new algorithm development for moving boundaries and immersed bodies. Immersed moving bodies - UNM.
 - Mixed element types - UNLV.
 - Turbulence modeling – LANL, Purdue, UNLV.
 - Parallel constructions – Matrix solver already developed for massively parallel constructions (All).
- Conjugate Heat Transfer (CHT) modeling
 - Develop partitioning algorithms for solid domain for parallel computing
 - Perform simulation using multiple processors
 - Conduct combustion modeling
 - Test the code in practical bowl-in-piston geometry – challenges in partitioning complex geometry of the solid domain

• Improving the current algorithms

- Increase robustness - generic method.
- Simulations with higher resolution.
- Use of overset parts/grids.
- Good candidate: Unstructured grid, precisely locate body.
 - 2nd Order in space.
 - Grid is of body only, fluid only.
 - Boundary condition update
- Movie of ball/fluid interaction*
 - Juan Heinrich (University of New Mexico).



*Used with permission from Juan Heinrich

- **Accurate, Robust and well Documented algorithms**
 - Developing and implementing robust and extremely accurate algorithms in KIVA-4 architecture – PCS/CBS *hp-adaptive* FEM.
 - Reducing model's physical and numerical assumptions.
 - Measure of solution error: resolution when and where required.
 - New algorithm requiring less communication, no pressure iteration, an option for explicit: newest architectures providing super-linear scaling.
 - More robust and accurate moving parts algorithms in development.
 - Lagrangian Frame for grid movement.
 - Conjugate Heat Transfer
 - More accurate prediction in wall film and its effects on combustion and emissions under PCCI conditions with strong wall impingement.
 - Validation in progress for all flow regimes
 - With Multi-Species
 - Starting spray and chemistry model incorporation.
- **Cut-Cell grid Generation and Implementation**
 - Quickly generate grids from CAD surfaces of complex domains. New algorithm has been developed, more generic
 - Cubit Grid interface being developed for boundary conditions implementation.
 - Discussions with Sandia about incorporating LANL cut-cell ideas into Cubit

Technical Back-Up Slides

(Note: please include this “separator” slide if you are including back-up technical slides (maximum of five). These back-up technical slides will be available for your presentation and will be included in the DVD and Web PDF files released to the public.)

- FEM Discretization for PCS or CBS

- Velocity predictor

$$\{\Delta \mathbf{U}_i^*\} = -\Delta t [\mathbf{M}_v^{-1}] \left[[\mathbf{A}_u] \{\mathbf{U}_i\} + [\mathbf{K}_{\tau u}] \{\mathbf{U}_i\} - \{\mathbf{F}_{v_i}\} - \frac{\Delta t}{2} ([\mathbf{K}_{char}] \{\mathbf{U}_i\} - \{\mathbf{F}_{char_i}\}) \right]^n$$

where $\{\Delta U_i^*\} = \{U_i^*\} - \{U_i^n\}$

- Velocity corrector (*desire this*)

$$U^{n+1} - U^* = \Delta t \frac{\partial P'}{\partial x_i} \quad \text{and} \quad \{U_i^*\} \text{ is an intermediate}$$

- How do we arrive at a corrector preserving mass/continuity?

- Continuity

$$\frac{\partial \rho}{\partial t} = -\frac{\partial \rho u_i}{\partial x_i} = -\frac{\partial U_i}{\partial x_i} \quad \frac{\rho^{n+1} - \rho^n}{\Delta t} = -\frac{\partial U_i'}{\partial x_i}$$

Define $U' = \theta_1 U^{n+1} + (1 - \theta_1) U^n$ with a level of implicitness

Desire $U^{n+1} - U^* = \Delta t \frac{\partial P'}{\partial x_i}$ *Let* $U_i' = \theta_1 \left(-\Delta t \frac{\partial P'}{\partial x_i} + U_i^* \right) + (1 - \theta_1) U_i^n$

Then $\frac{1}{c^2} \Delta P = \Delta \rho = -\Delta t \frac{\partial U_i'}{\partial x_i} = -\Delta t \frac{\partial}{\partial x_i} \left[\left(\theta_1 (-\Delta t) \frac{\partial P'}{\partial x_i} + \theta_1 U_i^* \right) + (1 - \theta_1) U_i^n \right]$

Density Solve (Pressure when incompressible flow)

So
$$\frac{1}{c^2} \Delta P = \Delta \rho = -\Delta t \frac{\partial U_i'}{\partial x_i} = \left[\left(\Delta t^2 \theta_1 \frac{\partial^2 P'}{\partial x_i^2} - \Delta t \theta_1 \frac{\partial U_i^*}{\partial x_i} \right) - \Delta t (1 - \theta_1) \frac{\partial U_i^n}{\partial x_i} \right]$$

Let $P' = \theta_2 P^{n+1} + (1 - \theta_2) P^n$ with some level of implicitness

recall

$$\Delta U^* = U^* - U^n$$

Then
$$\frac{1}{c^2} \Delta P = \Delta \rho = -\Delta t \frac{\partial U_i'}{\partial x_i} = \Delta t^2 \theta_1 \left(\theta_2 \frac{\partial^2 P^{n+1}}{\partial x_i^2} + (1 - \theta_2) \frac{\partial^2 P^n}{\partial x_i^2} \right) - \Delta t \left(\theta_1 \frac{\partial \Delta U_i^*}{\partial x_i} + \frac{\partial U_i^n}{\partial x_i} \right)$$

and $\Delta P = P^{n+1} - P^n$

Density then
$$\Delta \rho - \theta_2 \frac{\partial^2 \Delta P}{\partial x_i^2} = \frac{1}{c^2} \Delta P - \theta_1 \theta_2 \frac{\partial^2 \Delta P}{\partial x_i^2} = \Delta t^2 \theta_1 \frac{\partial^2 P^n}{\partial x_i^2} - \Delta t \left(\theta_1 \frac{\partial \Delta U_i^*}{\partial x_i} + \frac{\partial U_i^n}{\partial x_i} \right)$$

FEM Matrix form
$$\left(\left[\mathbf{M}_p \right] + \Delta t^2 c^2 \theta_1 \theta_2 \mathbf{H} \right) \{ \Delta \rho_i \} = \left(\left[\frac{\mathbf{M}_p}{c^2} \right] + \Delta t^2 \theta_1 \theta_2 \mathbf{H} \right) \{ \Delta P_i \} = \Delta t^2 \theta_1 \mathbf{H} \{ P_i^n \} - \Delta t \left(\theta_1 \mathbf{G} \{ \Delta \mathbf{U}_i^* \} + \mathbf{G} \{ \mathbf{U}_i^n \} \right) - \Delta t \{ \mathbf{F}_{P_i} \}$$

Now $P^{n+1} = \Delta P + P^n$

recall $P' = \theta_2 P^{n+1} + (1 - \theta_2) P^n = \theta_2 \Delta P + P^n$

Then
$$\Delta U_i = U^{n+1} - U^n = \Delta U * -\Delta t \frac{\partial P'}{\partial x_i} = \Delta U * -\Delta t \left(\theta_2 \frac{\partial \Delta P}{\partial x_i} + \frac{\partial P^n}{\partial x_i} \right)$$

FEM Matrix form
$$\{\Delta \mathbf{U}_i\} = \{\Delta \mathbf{U}^*\} - \Delta t [\mathbf{M}_u^{-1}] \left(\theta_2 [\mathbf{G}] \{\Delta p_i\} + [\mathbf{G}] \{p_i^n\} \right)$$

where
$$\{\mathbf{U}_i^{n+1}\} = \{\Delta \mathbf{U}_i\} + \{\mathbf{U}_i^n\}$$

final mass conserving velocity
$$u^{n+1} = U^{n+1} / \rho^{n+1}$$

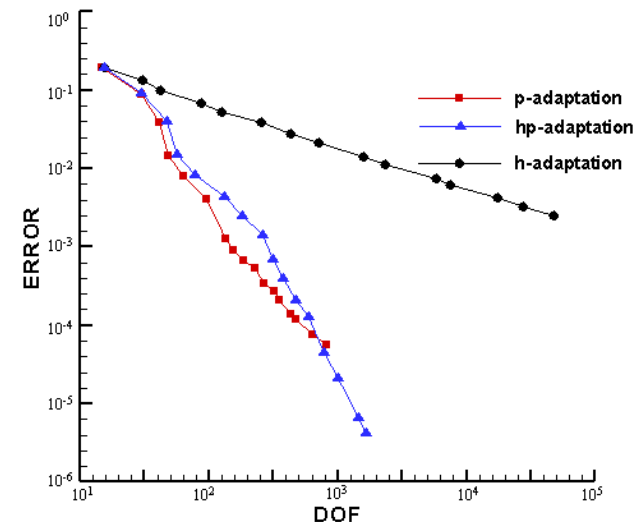
hp-adaptive methods for KIVA a CBS FEM method

- Why *hp*-adaptive grid
 - The use of *h*-adaptation can yield accurate solutions and rapid convergence rates.
 - Important when encountering singularities in the problem geometry.
 - Exponential convergence when higher-order, *hp*-adaptation
 - Error bounded by the following well known relation

$$\|u - u_h\|_m \leq ch^{k+1-m} \|u\|_r$$

'*u*' is assumed smooth in an H^{k+1} Sobolev norm, *m* is norm space, $r=k+1$, degree of integrable derivatives in *H*.

- Convergence of *hp* about same as *p*.
Speed of solution is better for *hp*,
since the higher-order polynomials
are used judiciously.
 - First perform *h*, then *p* for an *hp* scheme



Adaptation and Error – the driver for resolution

$$\|e_v\| = \left(\int_{\Omega} e_v^T e_v d\Omega \right)^{1/2} \quad L_2 \text{ norm of error measure}$$

$$\|e_v\|^2 = \sum_{i=1}^m \|e_v\|_i^2 \quad \text{Element error}$$

$$\eta_v = \left(\frac{\|e_v\|^2}{\|V^*\|^2 + \|e_v\|^2} \right)^{1/2} \times 100\% \quad \text{Error distribution}$$

$$\bar{e}_{avg} = \bar{\eta}_{max} \left[\frac{(\|V^*\|^2 + \|e_v\|^2)}{m} \right]^{1/2} \quad \text{Error average}$$

$$\xi_i = \frac{\|e\|_i}{\bar{e}_{avg}} \quad \text{Refinement criteria}$$

$$p_{new} = p_{old} \xi_i^{1/p} \quad \text{Level of polynomial for element}$$

▪ Error measures:

- Residual, Stress Error, etc..

▪ Typical error measures:

- Zienkiewicz and Zhu Stress
- Simple Residual
- Residual measure
 - How far the solution is from true solution.
 - “True” measure in the model being used to form the residual.
 - If model is correct, e.g., Navier-Stokes, then this is a measure how far solution is from the actual physics!